

Icefield Instruments Inc.
#300-116 Galena Rd
Whitehorse, Yukon CANADA
Y1A 2W6

tel: (867) 633-4264
fax: (867) 633-4217
e-mail: info@icefield.yk.ca
web: <http://www.icefield.yk.ca>

User Manual for the ECLIPSE Ice Coring Drill

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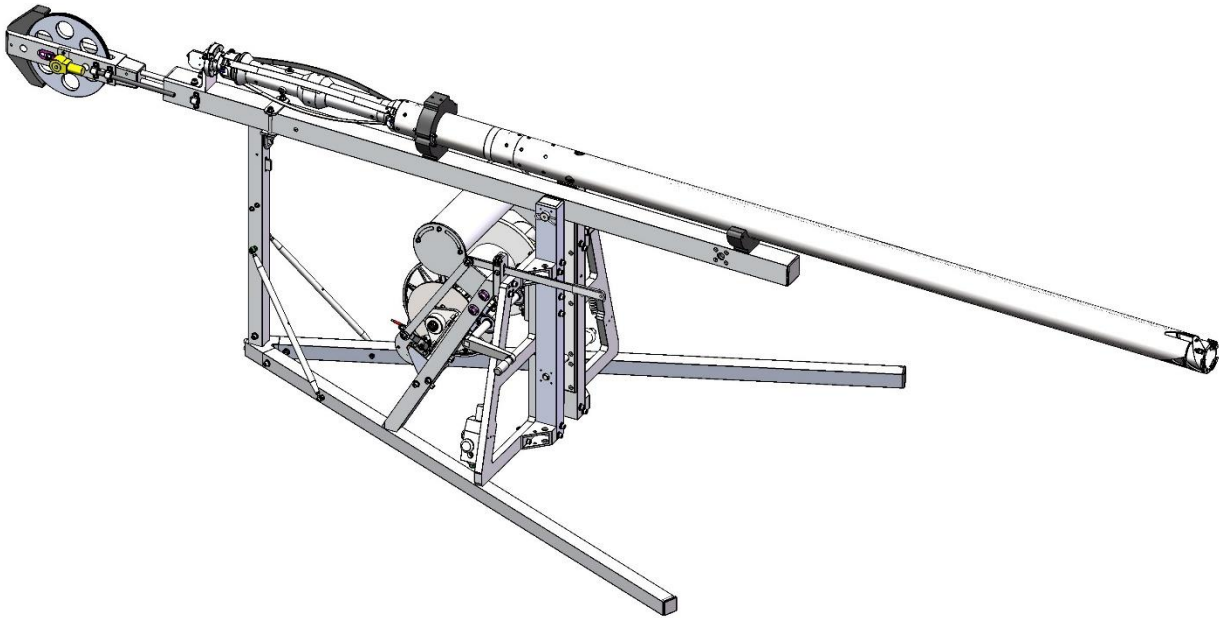


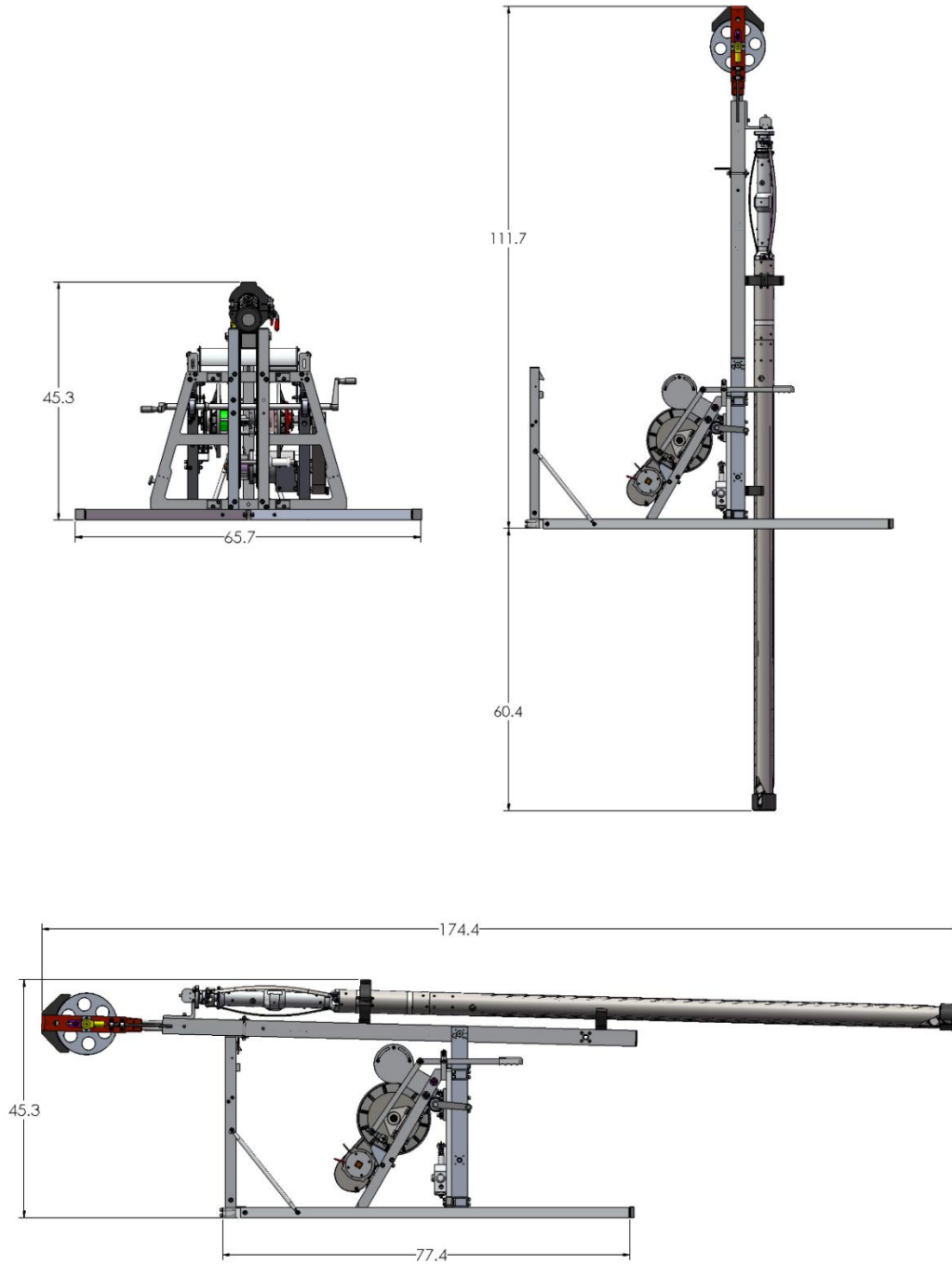
Table of Contents

1	Overall Dimensions:.....	4
2	Assembly instructions	5
2.1	General Notes.....	5
2.2	Winch Frame Assembly	6
2.3	Level Winder Assembly	14
2.4	Boom Assembly	15
2.5	Control Panel Connections	16
2.6	Winch Cable Set-Up	20
2.7	Level Winder Synchronization	20
2.8	Drill Anti-torque Section	25
2.9	Drill Assembly	35
3	Operating Instructions	42
3.1	General Comments.....	42
3.2	Drilling Core	43
3.3	Record keeping.....	46
3.4	Zero depth.....	46
3.5	Encoder and depth counter.....	46
4	Tips	47
4.1	Drilling a straight hole.....	47
4.2	Keeping the drill cold.....	48
4.3	Cleaning the drill	48
4.4	Keeping the drill clean.....	48
4.5	Over Night Storage	49
4.6	Setting the Anti-Torque Spring Tension.....	49
4.7	“Feeling” the drill	49
4.8	Cutter heel choice	49
4.9	Losing the lock pins	50
4.10	Drilling without a Cable Level Winder	50
5	Eclipse Ice Drill Optional Upgrades.....	50
5.1	Long Boom Assembly	50
5.2	Wet drill modifications	53
6	Routine Maintenance of ECLIPSE Ice Drill.....	60
6.1	Honing the Cutters and Core Dogs.....	60
6.2	Storing the Drill for the Season	60
6.3	Saline environments	60
6.4	Oil.....	61

6.5	Level Winder Maintenance	61
7	Troubleshooting	62
7.1	Drill motor will not start.....	62
7.2	Winch motor will not start.....	62
7.3	Depth counter runs in reverse.....	62
7.4	Drill motor is trying to rotate the barrel, but not working.....	62
7.5	Freeing a stuck drill.....	63
7.6	“Gum” in the sheave	63
7.7	Winch motor failure	63
7.8	Winch transmission failure	63
7.9	The drill does not advance.....	63
7.10	Programming the depth counter and tachometers	64
8	Tools and Spares	68
8.1	Supplied Tools List.....	68
8.2	Suggested Tools List	69
9	Drawings	73

1 Overall Dimensions:

The image below shows the dimensions of the short boom configuration in Inches. Approximate weight including wet drill sonde and spare parts is 590kg.



2 Assembly instructions

2.1 General Notes

- Unless otherwise noted, all the hardware/fasteners on this drill are of Imperial dimensions (fractional inches). Please refrain from using metric tools as damage to the unit may result.
- Many fasteners on this drill are secured using Loctite (a cyanoacrylate thread-locking compound). Red (permanent) Loctite is used, for example, on the screws holding the plastic flights onto the inner barrel. Blue (removable) Loctite is used on frame fasteners. If you suspect that a screw or bolt is not rotating because it has this material applied to it, you can heat the part with a torch to soften the locking compound. Take care not to damage plastic and/or rubber components.
- Frame fasteners are all stainless steel – where they attach to load-bearing aluminum parts, there is sometimes a steel Helicoil® thread insert used to strengthen the joint and to avoid thread wear on the aluminum. If you see evidence of thread damage on a fastener (the inserts are harder than the fastener), please replace the fastener as soon as possible.
- Stainless steel fasteners are prone to galling. The supplied anti-zeize compound should be applied to all fasteners.
- Assembling a large machine with many close-tolerance parts can be made much easier if fasteners are left a bit loose until all the fasteners are in place.

2.2 Winch Frame Assembly

- Figure 1 below shows the general layout of the drill when assembled. The drill shown consists of the short boom configuration in the horizontal position.

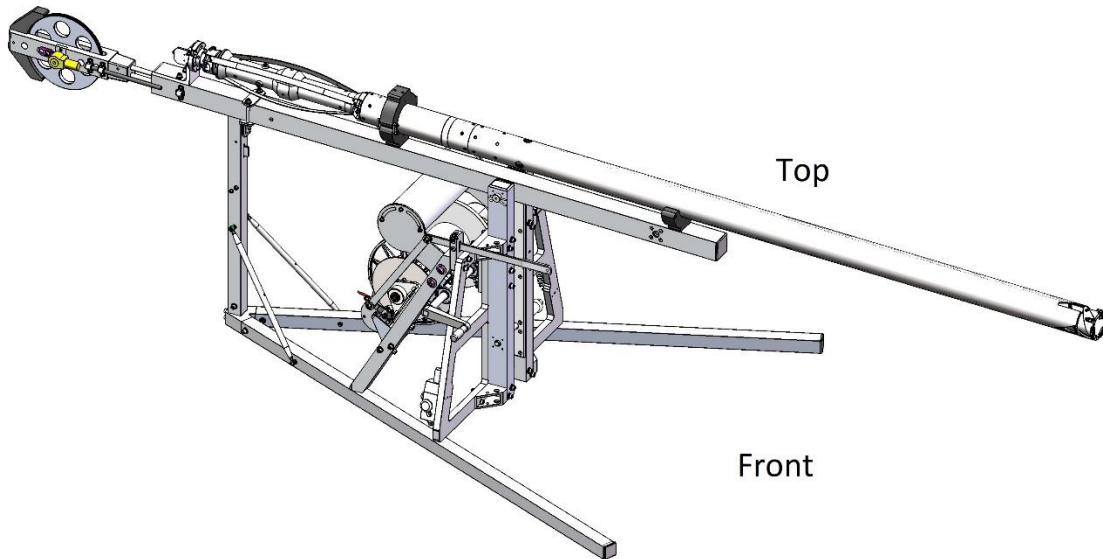


Figure 1 – Reference Frame

To have a base onto which to assemble other components it is suggested that the Winch Frame be assembled first. (Figure2)

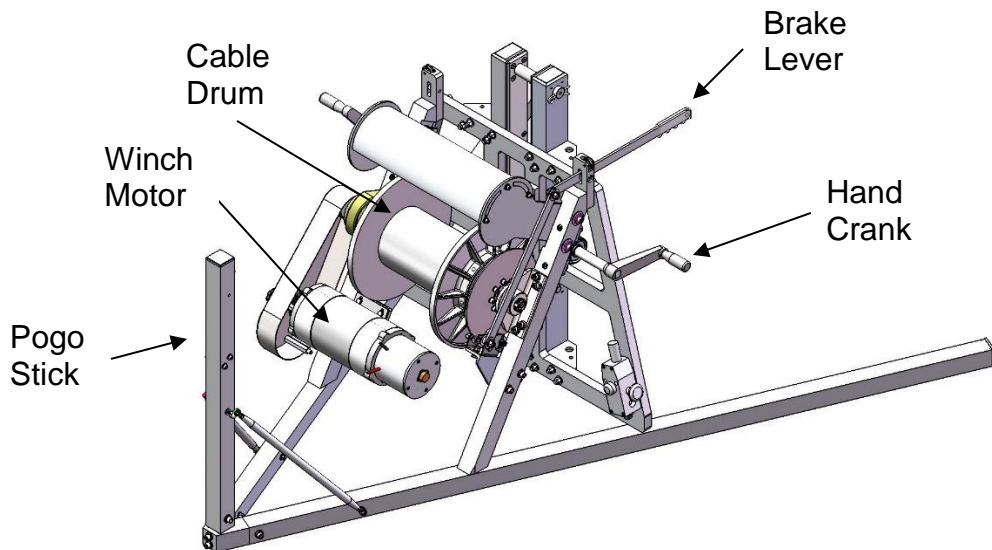


Figure 2– Winch Frame Assembly

2.2.1 Bare Frame Assembly

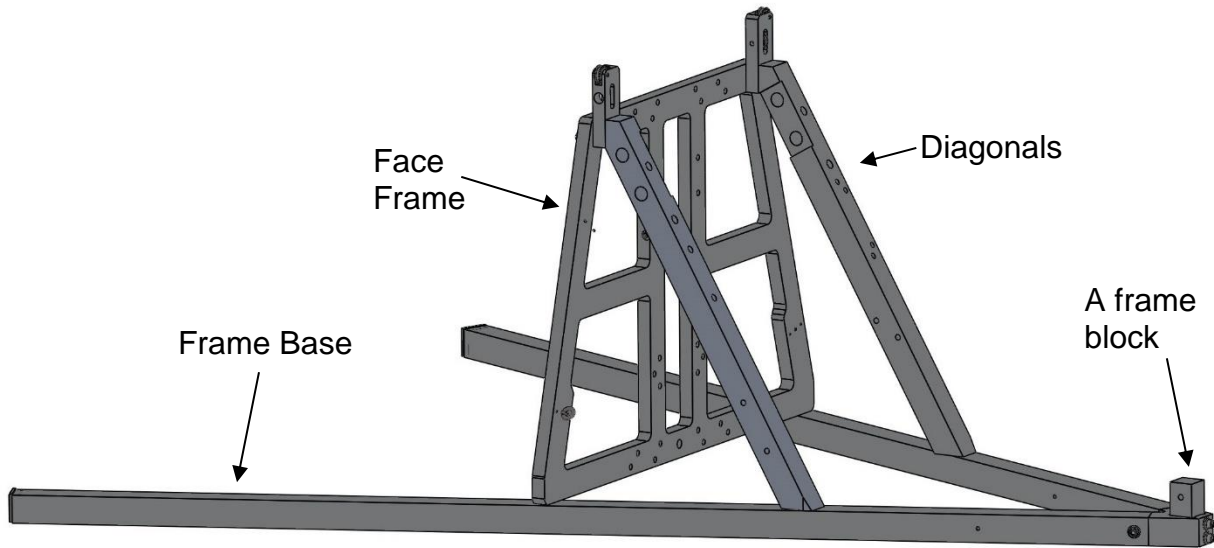


Figure 2 – Bare Frame Assembly

First Assemble the Frame Base. This consists of two long base frame members and one A frame block. Then attach the diagonal members to the Face frame and the face frame / diagonals members assembly to the base.

2.2.2 Mount the Emergency Stop Switch

Mount the E-Stop Switch onto the face frame and route the cable over the pulleys as shown below. The cable is attached to a hook on the other side of the face frame using a tensioning spring. The E-Stop should be tested for functionality when ever the drill is operated. The tension in the cable can be adjusted using the cable tensioner if required.

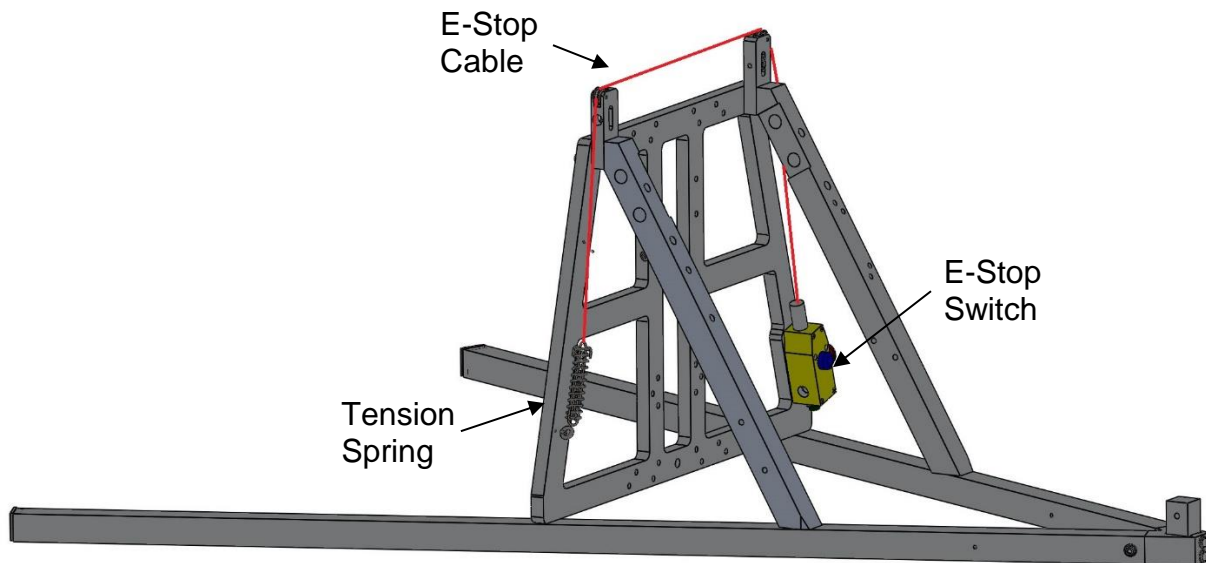


Figure 3 - E-Stop Assembly

2.2.3 Mounting the Cable Drum and Winch Motor

The winch motor and cable drum can now be mounted onto the frame. The input shaft of the cable drum should be on the right side of the winch, as shown. Figure 4 shows two chains installed. The right-hand chain (shown in foreground) is used to drive the level winder. If the drill has no level winder, then omit this chain. The second chain (the bottom is just visible in the photo) is for the hand crank. This second chain should always be installed.

Some users prefer to mount the Boom before the winch is mounted. A ratchet strap or other webbing can be used to lift and hang the winch from the boom. This can make it easier to lift and hold the heavy winch while mounting it to the frame.

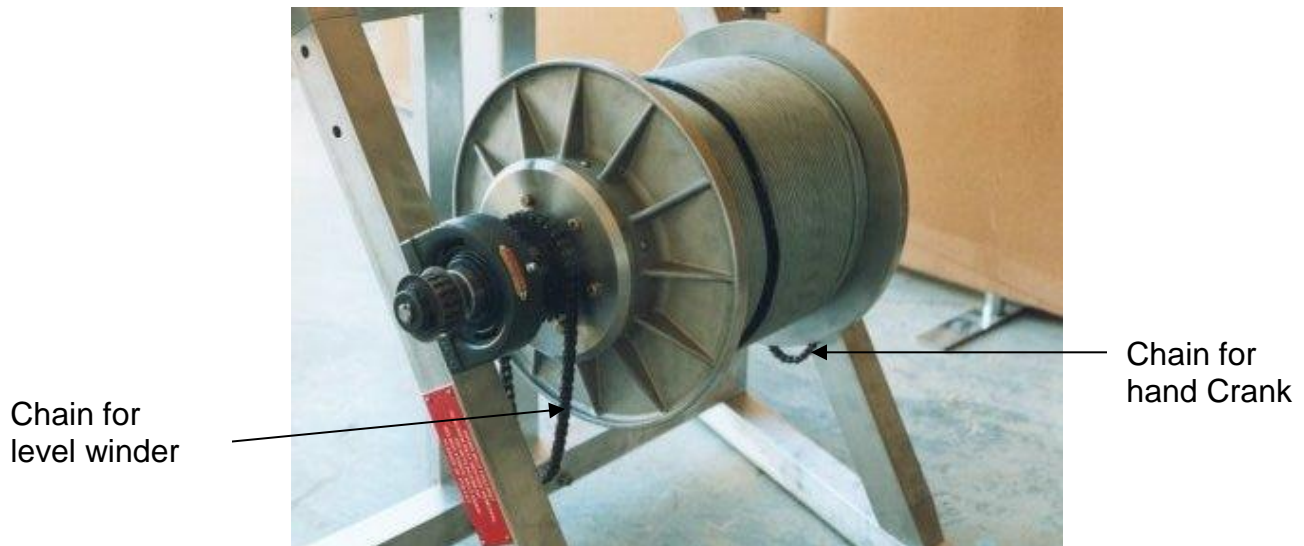


Figure 4 – Winch Cable Drum

Mount the winch Motor to the right diagonal frame member. Before tightening the mounting fasteners for the winch motor attach the drive belt to the motor and drum. Take care that the belt is not stretched and/or twisted when installed. The belt tension should be such that about 5mm deflection results from modest thumb pressure. Also ensure that the two pulleys are lined up so that the belt runs perpendicular to the shafts.



Figure 5 – Installing the Drive Belt

Attach belt cover plate on the diagonal and to the two posts attached to the winch motor using the supplied thumb screws.



Figure 6 – Installing the Cover Plate

2.2.4 Mounting the Pogo Stick

Mount the Pogo stick to the frame base. Also mount the Pogo Supports. The pogo supports can be lengthened or shortened by turning the support when its ends are held in place. In this way the pogo stick can be stiffened if required.



Figure 7 – Pogo Stick Installation

2.2.5 Mounting the Boom Supports

Mount the Boom Supports to the front of the Face Frame. Also insert the Boom Locking Pin into the bottom of the boom supports. It is suggested that this pin be tied to the frame or another object using the supplied cord. This will avoid dropping the pin down the drill hole or losing the pin.

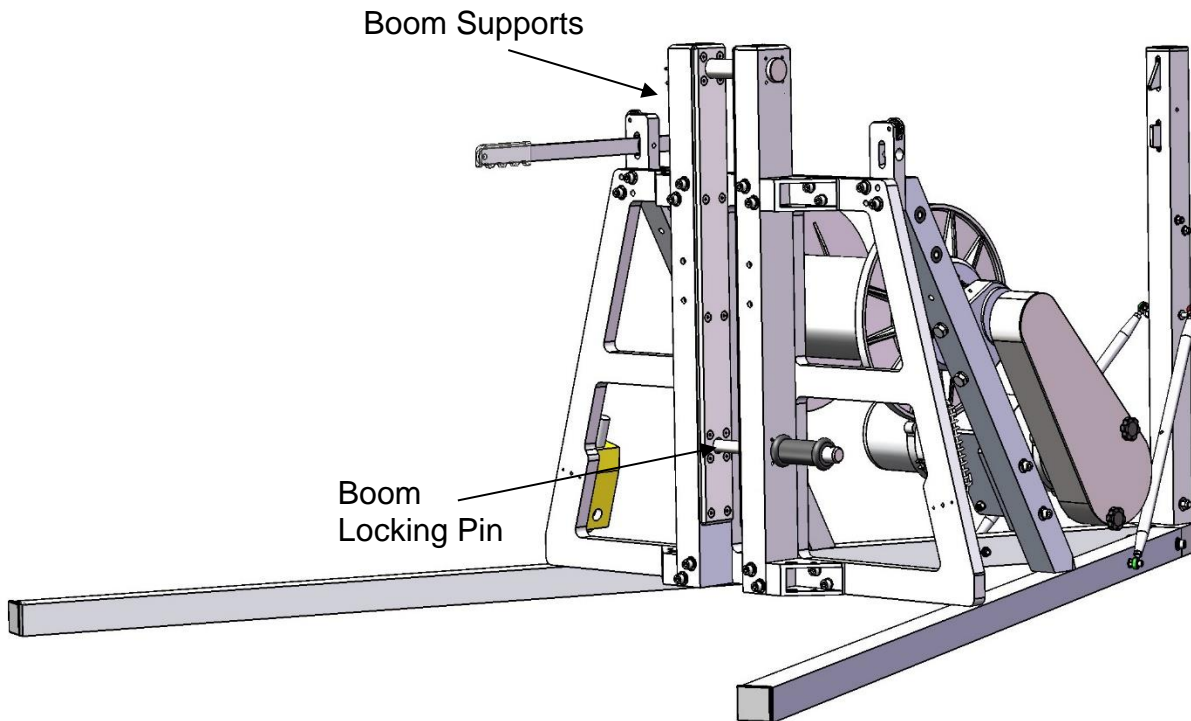


Figure 8 – Installing the Boom Supports

2.2.6 Mounting the Hand Brake and Hand Crank

Attach the Brake Assembly (Brake caliper and Brake Handle) to the frame as shown in Figure 9. Attach the bearing blocks (with Crank Shaft attached) for the hand crank on the diagonal and upright members of the frame. The small gear on the axle should be positioned to line up with the large gear on drum axle (next to the brake disk). It is recommended that the crank handles only be installed if problems with raising the drill occur.

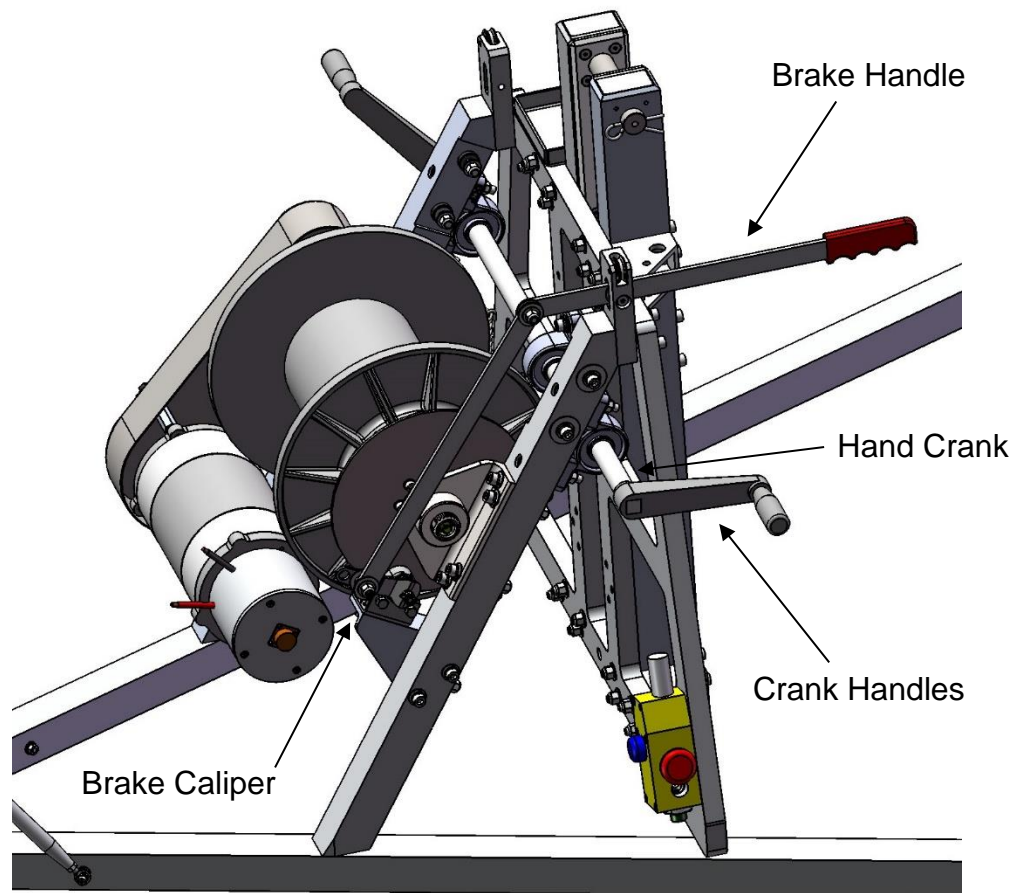


Figure 9 – Brake and Crank Installation

2.2.7 Mounting the Dummy Level Winder

The Level Winder Assembly is optional. If your drill does not come with a Level Winder a Dummy Level Winder will be supplied. Secure the dummy level winder in its place on the diagonal supports of the frame using the 3/8" spring pins provided. The semi-circular cover over the level winder serves to support the winch cable, and maintain tension on that cable when the mast is in the "down" position.

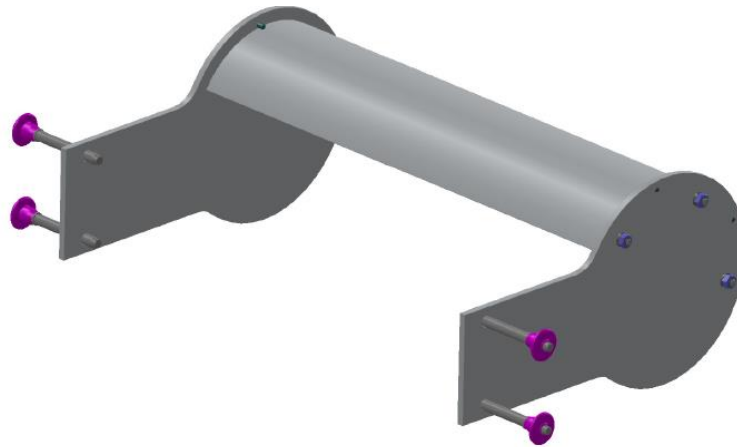


Figure 10 – Dummy Level Winder

2.3 Level Winder Assembly

The Level Winder Assembly is optional. If your drill does not come with a level winder skip to the next section.

The Level Winder Accessory Module for the Eclipse II Ice Coring Drill System's winch provides a virtually self-contained mechanical system for evenly wrapping electromechanical cable onto the drum of the Eclipse II winch. The Level Winder is shipped fully assembled, lubricated, and ready for installation.

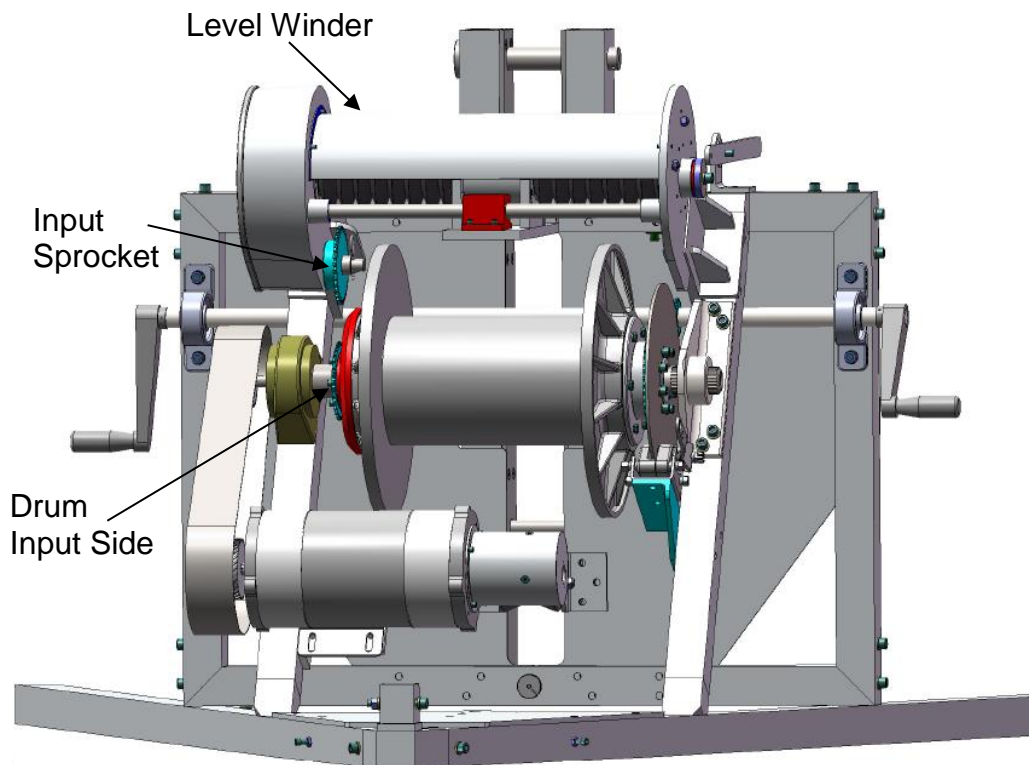


Figure 11 – Installation of Level Winder

Ensure that the drive-chain for the Level Winder has been previously attached to the winch drum at the input side. If not in place already, some disassembly will be required to fit it now.

Mounting the Level Winder onto the frame is best done with two people. Lift the level winder into place, and tip the chain sprocket end downward to loop the drive chain over the input sprocket. Then mount the Level winder in place using the supplied 3/8" X 2" spring pins. Note mounting nuts and bolts may be provided with the drill. If so these can be used to secure the level winder, but it is suggested that spring pins are used to locate one side of the level winder to allow for movement between the level winder and frame.

2.4 Boom Assembly

This section outlines the assembly of the standard boom configuration.
If your drill has a long boom configuration refer to section 5.1.

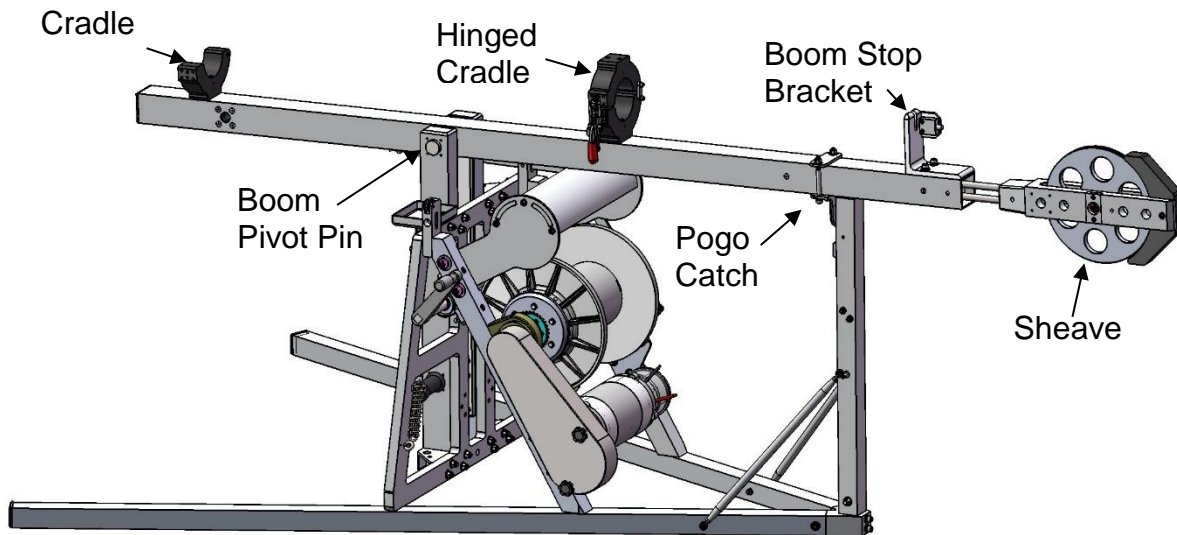


Figure 12 – Short Boom Assembly

Mount the Boom onto the frame using the Boom Pivot Pin. The Boom Pivot Pin is secured with a supplied hairpin style cotter pin.

Mount the Boom Stop Bracket at the back end of the boom as shown in Figure 12. Do not over tighten the mounting screws for the bracket. This will deform the boom and cause interference with the sheave.

Mount the cradles as shown above. The hinged cradle is located closer to the sheave. Also mount the Pogo Catch as shown. Ensure that it is properly located to catch the pogo stick and prevent the boom from swinging into a vertical position.

2.5 Control Panel Connections

There are four electrical cables provided. They are the AC Power Cable, Winch Frame Cable, Winch Motor Cable, and Mast Cable.



Figure 13 – Control Panel Back Panel

Figure 13 above shows the back panel of the control panel. This is where all of the electrical cables are plugged into the control panel (the exact look of the back panel might differ).

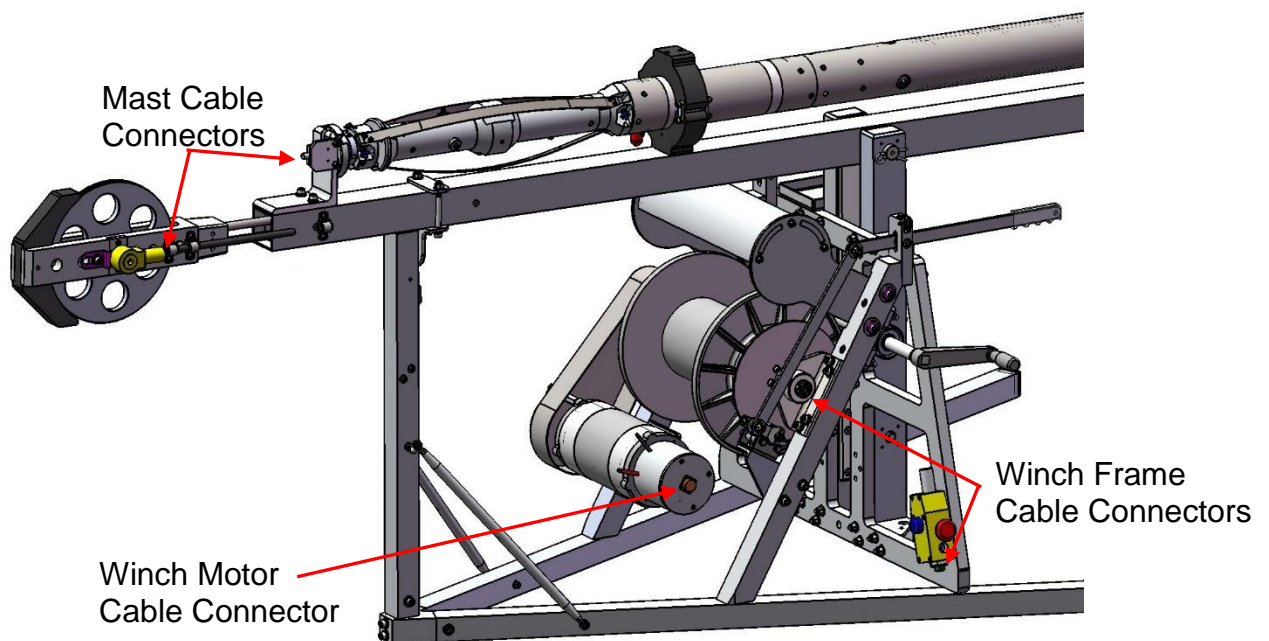


Figure 14 – Drill Cable Connection Locations

2.5.1 AC Power Cable

The AC Power Cable is blue and yellow in color. It has a 3 socket mil connector at one end and is blank at the other. The blank end of the cable must be terminated with the style of 230V plug that is required for the type of power source (ex, diesel generator) used by the user. The AC power cable is connected to the control panel and the power source to be used.

Wiring of the mains power cables is as follows:

Pin	Colour	Function
A	Black	Hot
C	White	Neutral
B	Green	Frame Ground

2.5.2 Internal Drill motor wiring

Internal to the drill (e.g., between the drill motor assembly and the bottom of the anti-torque section), and at the spline coupling on the winch drum shaft, the wiring is as follows:

The cable plug is an MS3116F8-4S (or MS3116E8-4S if there is no strain relief) connecting to an MS3112E8-4P receptacle.

Pin	Function
A	Drill Power
D	Drill Return (ground). This pin is also connected to the drill wireline armour and the entire frame of the drill system.
B	Tachometer signal
C	Tachometer return (ground)

2.5.3 Winch Frame Cable

The Winch Frame Cable is black, has a small 8 socket connector at one end and two mil connectors at the other end. The two connectors at the other end are a 2 socket and a 4 socket. The 4 socket connector is connected to the axle of the drum connector, and the 2 socket connector is connected to the bottom side of the top frame cross member as shown in Figure 14.

The winch frame cable connects the control box to the winch drum and emergency stop switches. . The plug at the control box is an MS3116F12-8P mating with an

MS3112E12-8S receptacle. The plugs on the other end of this “two-headed” cable are noted in the table.

Pin (8-pin)	Pin (at device)	Function
A	C (PT06E-12-4S-SR)	Drill Emergency Stop
G	C (MS3116F8-4S)	Tachometer return (ground)
B	B (MS3116F8-4S)	Tachometer signal
H	D (PT06E-12-4S-SR)	Drill Emergency Stop
E	A (PT06E-12-4S-SR)	Winch Emergency Stop
F	B (PT06E-12-4S-SR)	Winch Emergency Stop
C	A (MS3116F8-4S)	Drill power
D	D (MS3116F8-4S)	Drill return (ground)

2.5.4 Winch Motor Cable

The Winch Frame Cable is the shortest and thickest black cable. It has a large 8 socket connector at each end. One end is connected to the control panel and the other to the winch motor.

The winch cable connects the control panel to the brake/tachometer housing on the winch motor (cable plugs MS3116F16-8P/S mating with receptacles MS3116E16-8P/S).

Pin	Function
A	Tachometer signal
B	N/C
G	Tachometer Ground
F	Brake solenoid
C	Brake Solenoid
E	Winch Power
D	Winch Return
H	N/C
Frame	Ground

2.5.5 Mast Cable

The Mast cable is the longest one. It has a 8 socket connector at one end that is connected to the control panel. The other end has one yellow lead and one black one. The yellow lead is connected to the limit switch at the top of the boom. The black lead is connected to the encoder located on the sheave. Velcro straps are provided to secure the cable to the mast. Ensure that all cables are secured so as to not get damaged during drill operation.

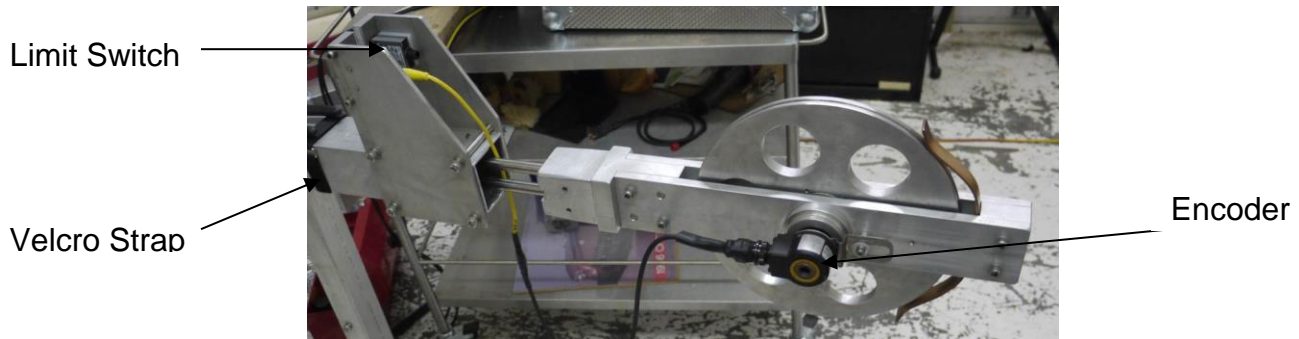


Figure 15 – Mast Cable Connections

The mast cable connects the control box to the encoder and drill stop switch. The plug at the control box is an MS3116F12-8P mating with an MS3112E12-8S receptacle. The plugs on the other end of this “two-headed” cable are noted in the table.

Pin (8-pin)	Pin (at device)	Function
A	B (97-3106A-14S-6S)	Encoder +12VDC
G	A (97-3106A-14S-6S)	Encoder Ground
B	E (97-3106A-14S-6S)	Encoder A-channel
H	D (97-3106A-14S-6S)	Encoder B-channel
E	2 (Molex 1200650255)	Mast stop switch
F	1 (Molex 1200650255)	Mast stop switch
C		N/C
D		N/C

2.6 Winch Cable Set-Up

Before the winch cable is terminated at the drill (as described in section 2.8), it is recommended that the winch cable be routed through the drill. If a Level winder is included, it is also suggested that the level winder be synchronized with the cable on the drum. To avoid bad cable layers wrap, it is a good idea to lay the cable out all the way on the ice and get some heavy people on a sled to take a "ride" (using their feet as brakes) back to the winch to ensure that tension is good and even, a shim could be added at the first wrap. The cable should be perfectly wrapped around the drum with no layers diving under the underneath one. See picture below.



Figure 16 – Drum Winding

2.7 Level Winder Synchronization

If a level winder is provided with the drill, it is important that it be synchronized with the cable on the Winch Drum.

With the cable wrapped onto the drum (if necessary, tidy this up manually) apply electrical power to the winch drive and slowly pay-out a small length of cable from the drum while noting in which direction the shuttle is moving.

Caution: ensure that the cable is secure so that a large amount of cable does not spring from the drum.

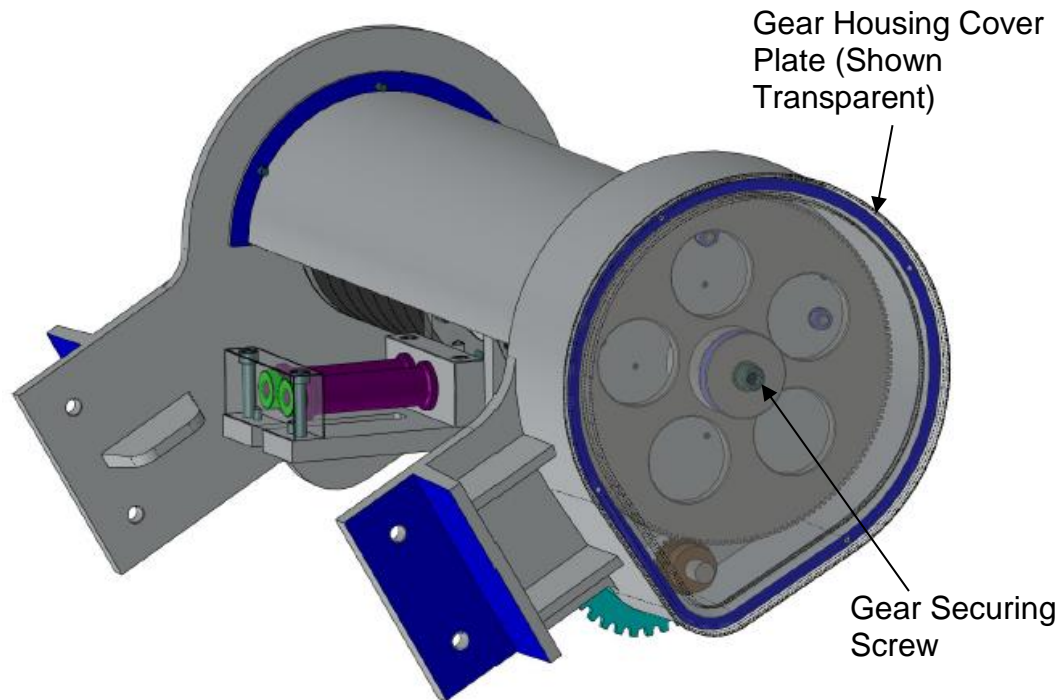


Figure 17 – Level Winder Assembly, Gear Side

Remove the gear-housing cover plate. Loosen, but do not remove the socket head cap screw at the center of the large gear (Figure 17). This allows the reverser screw to rotate independently of the gear.

With everything else stopped, rotate the reverser-screw by inserting a hex-wrench into the socket head cap screw on the idler side of the reverser screw (Figure 18 below). Rotate the reverser screw to move the gap between the Level Winder Fairlead Rollers directly above the winch cable and so that the Level Winder Shuttle is moving in the same direction as the Winch Cable.

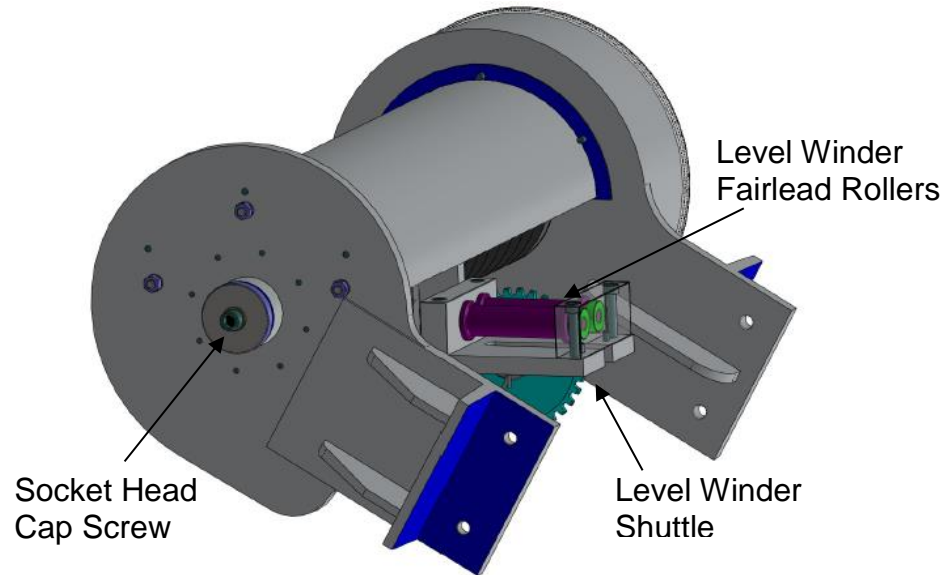


Figure 18 – Level Winder Assembly, Idler Side

Once set, lock the synchronization by holding the reverser screw at the non-gear end with a hex-wrench, while tightening the hex-socket bolt at the gear end. Replace the gear-box cover plate.

After the initial (loosely wound and disturbed) cable has been spooled out, it may be necessary to re-synchronize the LWM, but this should only amount to a small positional adjustment.

2.7.1 Routing the Winch Cable

Using the control panel slowly turn the winch cable drum in the (down position) to dole out a few meters of cable. **Caution:** ensure that the cable is secure so that a large amount of cable does not spring from the drum.

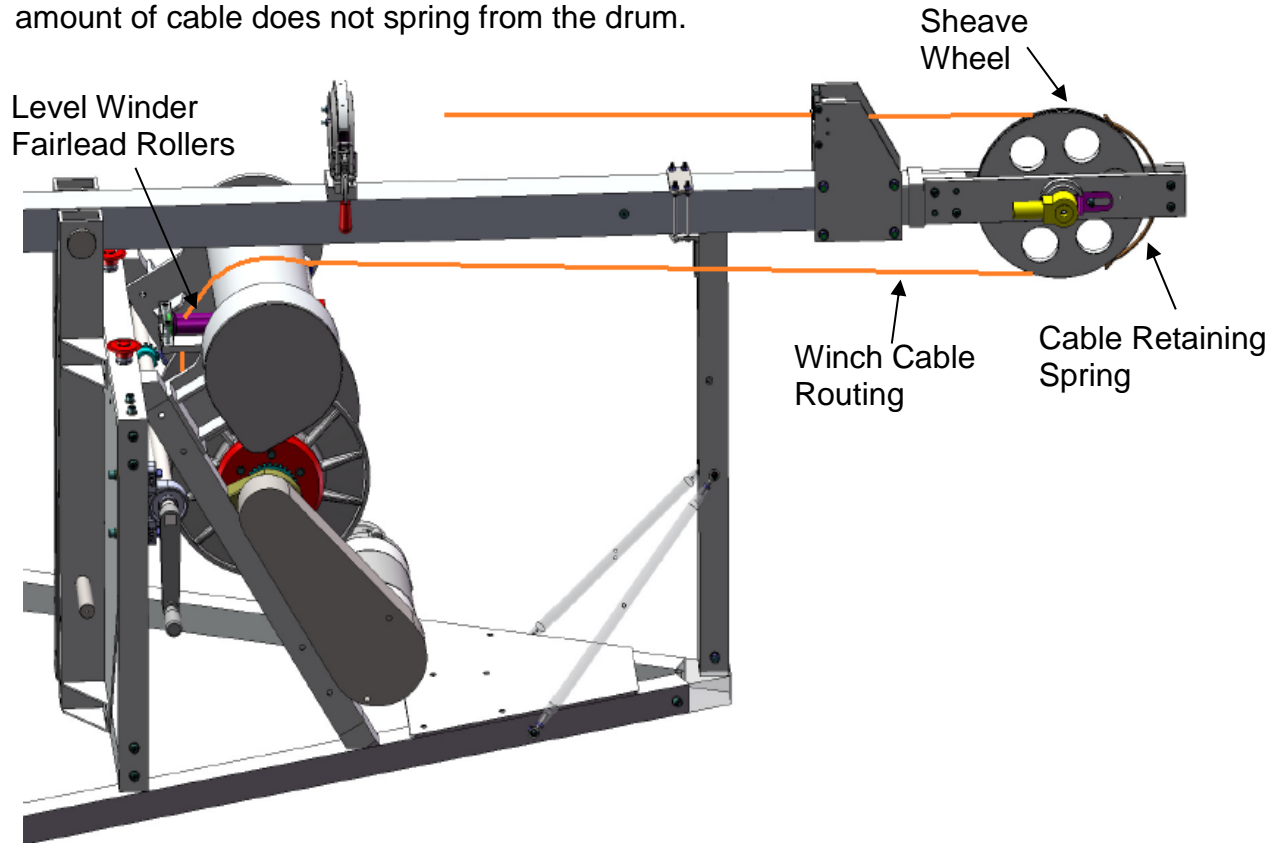


Figure 19 – Winch Cable Routing

Route the winch cable as shown in Figure 19 above. The cable is routed through the Fairlead rollers on the level winder (if a level winder is included with the drill). The winch cable is also routed over the level winder cover (or dummy level winder cover) and around the Sheave Wheel. Ensure that the cable is secure in the groove of the Sheave Wheel and held in place by the Cable Retaining Spring.

2.7.2 Routing the Winch Cable if Cable is Already Terminated

It is suggested that the winch cable be route through the Level Winder and Sheave before terminating the cable at the drill (as described in section 2.7.1). If the cable has already been terminated it is still possible to route the winch cable.

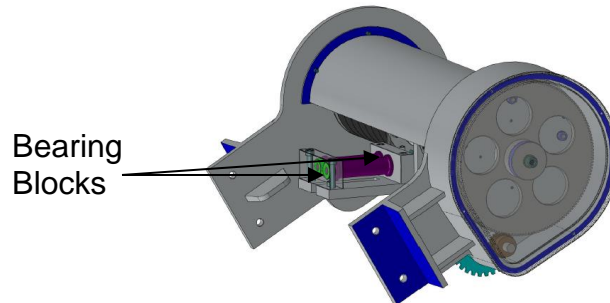


Figure 20 – Fair Lead Bearing Blocks

The cable can be routed through the Fairlead Rollers in the Level Winder by loosening the two pairs of bolts which hold the two bearing blocks at the ends of the rollers (Figure 20). These bearing blocks are also held in place by a pair of short (hidden) dowel pins which accurately locate the blocks. It is possible to loosen the innermost blocks' bolts enough to lift the block off of the dowel pins, and tilt it enough to free the front block and one of its rollers. Disassembled this far, it is possible to thread the cable into the slot and reassemble the fairlead roller unit.

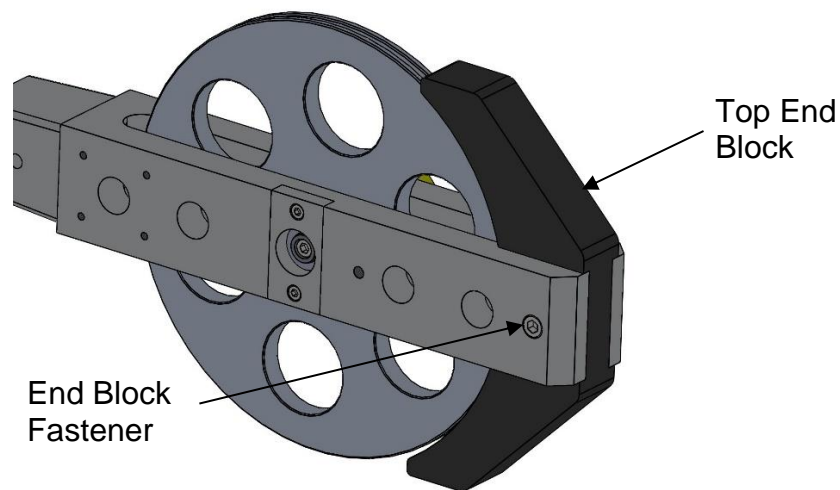


Figure 21 – Sheave Top End Block

The winch cable can be routed onto the Sheave Wheel by removing the fastener holding the Sheave Top End Block (see Figure 21). This will allow the top end block to be removed and the cable to be routed onto the wheel.

2.8 Drill Anti-torque Section

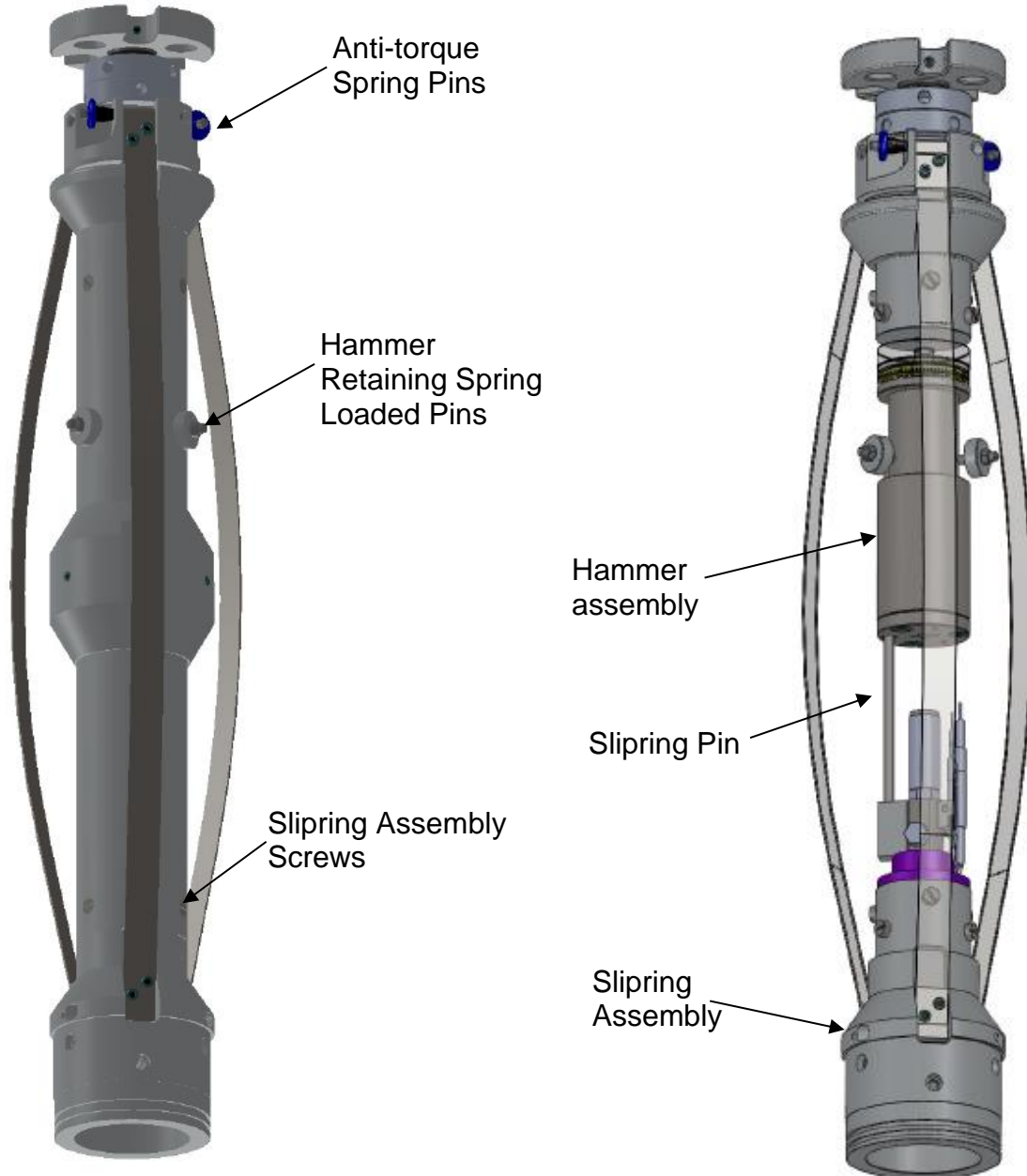


Figure 22 – Anti-torque Assembly

2.8.1 Winch Cable Termination

Warning: before the winch cable is terminated ensure that the winch frame cable is unplugged!

Before terminating the winch cable the winch cable should be passed through the level winder and sheave assemblies as described in section 2.7.1.

The winch cable termination mechanism is inside the anti-torque section of the drill. The termination is a pinch-type termination located inside the hammer

To attach the winch cable to the drill, the hammer assembly must first be removed from the anti-torque section. First remove the anti-torque spring pins near the top of the anti-torque assembly, and using a 1/4" Hex driver remove the six slip ring assembly screws (see Figure 22). The slip ring assembly can now be removed.

The hammer can also be removed from inside the anti-torque tube. There are three spring-loaded pins that must be retracted to release the hammer. Hammer Pin Retraction tools are provided to make this easier. Note some drills have a 3/8" screw holding the hammer in place instead of the spring-loaded pins. These screws can easily be removed using a 1/16" hex key.



Figure 23 – Hammer Pin Retraction Tool

Remove the hammer flange from the lower end of the hammer that contains the Evergrip termination. Thread the cable through the upper anti-torque assembly and the hammer and attach the cable to the Evergrip termination according to the manufacturers' instructions.

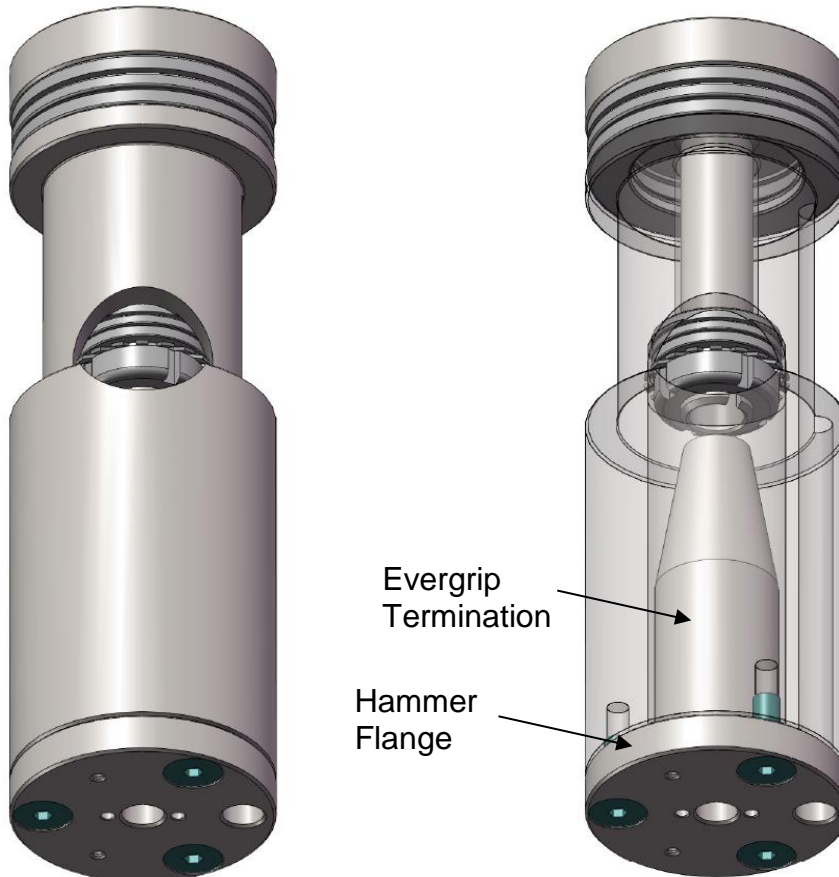


Figure 24 – Hammer Assembly

The termination kit is the Evergrip part number P/N 9006120-1, and the re-termination kit (does not include the body) is 9006120-1R. Installation instructions are included with each re-termination kit, but more information is available on the PMI website: www.pmiind.com/index.php?id=23.

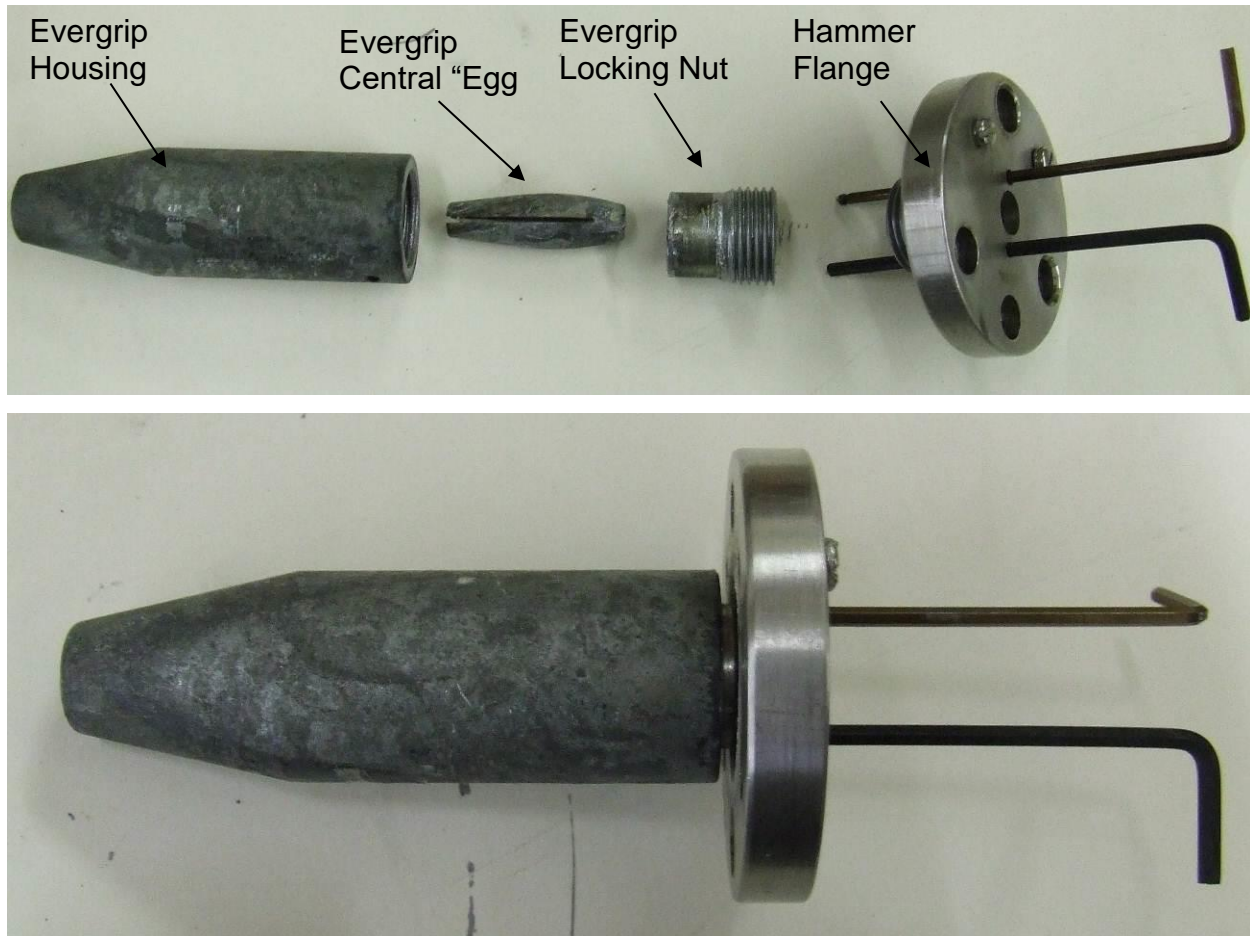


Figure 25 – Cable Grip Assembly

The two small holes in the base of the hammer can be used (together with the two pins (Allen keys) supplied with the Evergrip termination kit) as a wrench to tighten the overwraps onto the central “egg” (see pictures above). Make sure that while you are tightening the “egg”, the flange does not bottom out on the Evergrid housing, thereby giving you a false sense of having tightened up the egg.

Leave about 12” of winch cable conductors below the hammer for electrical termination. The strands of the cable armor should be cut off immediately below the termination and wrapped in tape to protect the conductors. The easiest way to cut the strands is using a Dremel tool with a parting disk, as shown in Figure 26.



Figure 26 – Winch Cable Preparation

When reassembling the hammer, make sure the 6mm (1/4") clearance hole in the flange and the corresponding hole in the hammer body are lined up – this hole accepts the pin on the slipping assembly that is attached to the bottom hinge block of the anti-torque section.

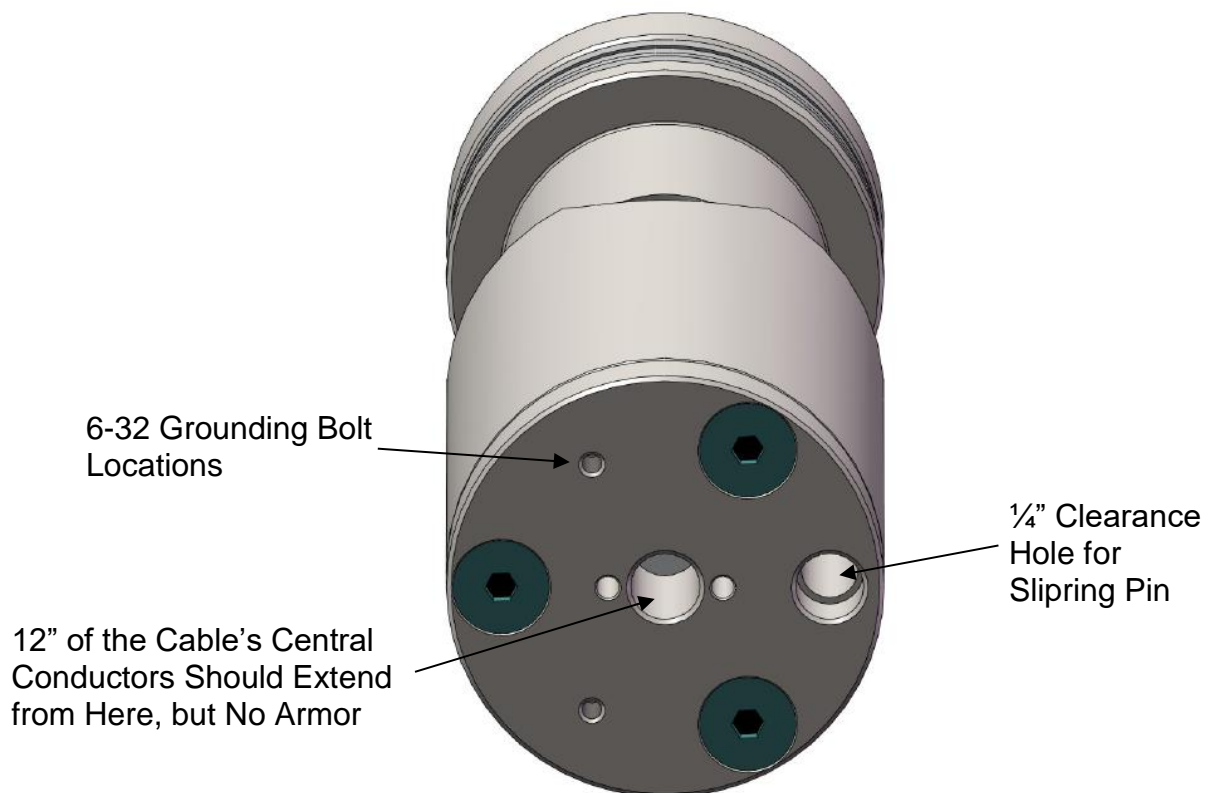


Figure 27 – Hammer Flange

2.8.2 Slipping Wiring

After the winch cable has been terminated using the Evergrip termination kit, the electrical connection of the winch cable can be completed. The winch cable is electrically connected to the top of the slipping assembly. Two male Seacon waterproof connectors are used to complete the connections. The table below outlines the connections that need to be made. The female Seacon connectors need to be soldered to the appropriate Winch cable conductors. The female Seacon connector used for the drill power is soldered to two winch cable conductors.

Winch Frame Cable Connector	Function	Slip Ring Wire Colour	Seacon Connector	Cable Conductor Colour
A	Drill power (uses two conductors!)	Red	Conn. 1 - White	Black and Red
B	Tachometer signal	Green	Conn. 2 - White	Green
C	Tachometer return	White	Conn. 2 - Black	White
D	Drill power return	Black	Conn. 1 - Black	Ring Terminal to Hammer

The connections made between the winching cable strands and the drill sonde's slipping are NOT in a watertight compartment. Voltages on the A/D circuit (drill motor) will reach up to 200VDC during drill operation. Make sure that you insulate the connections appropriately for your drilling conditions!

2.8.3 Verifying the Slipping Wiring (Test Box)

Since the slipping electrical connections are difficult to access, it is suggested that these connections be verified before the drill is reassembled. A wire tester box has been provided for this purpose (see Figure 28). Note that the tester box might be white or black.

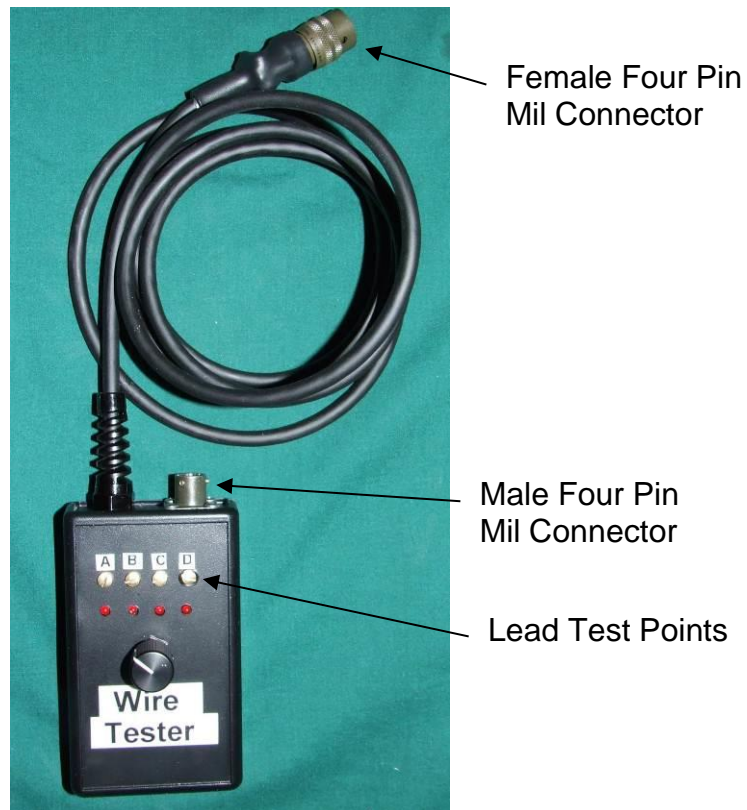


Figure 28 – Wire Tester Box

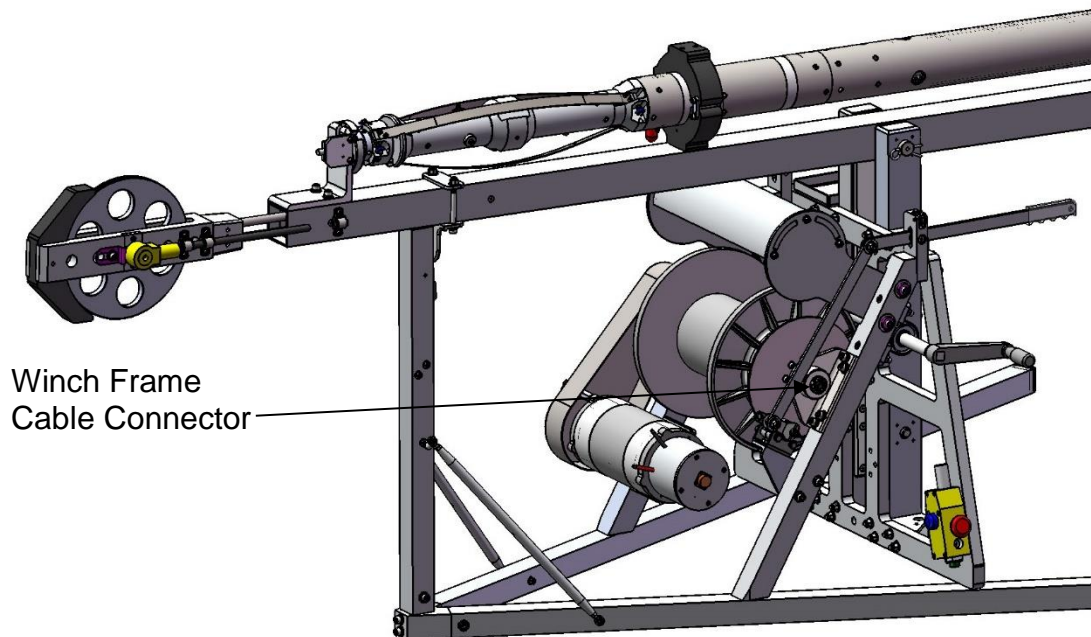


Figure 29 – Winch Cable Connector Location

The female connector is attached to the winch frame cable connector located on the axle of the drum assembly (see Figure 29 above). Each circuit can be selected using the center switch. For each selected circuit the red LED will light up if the circuit is complete.

To select the correct conductor from the four inside the wireline cable, connect the test box to the winch frame cable connector. Then select each circuit (A, B, C, and D) in turn. For each selection, touch the bare end of each wire to the screw next to the circuit label (e.g., "A"). If you have selected the correct conductor, the LED will illuminate. Keep in mind that two of the internal wireline conductors are connected to circuit "A", and that the wireline armor is connected to circuit "D". At the sliping, circuit "D" uses a separate ground wire.

As a final check after the sliping connections have been completed, the anti-torque to drill motor jumper (located at the bottom of the sliping assembly) can be plugged into the test male connector on the top of the Wire Tester. Select each circuit in turn to verify connections. Note also that circuits C and D (ground returns for drill tachometer and drill motor) are connected.

2.8.4 Re-Assembly

After the cable termination and wiring has been completed, the anti-torque assembly can be re-assembled. Make sure that the slip ring stir-stick is lined up with the clearance hole in the hammer assembly.

The anti-torque section can then be reassembled to the drill motor section. Firstly, connect the Anti-torque to Drill motor Jumper.

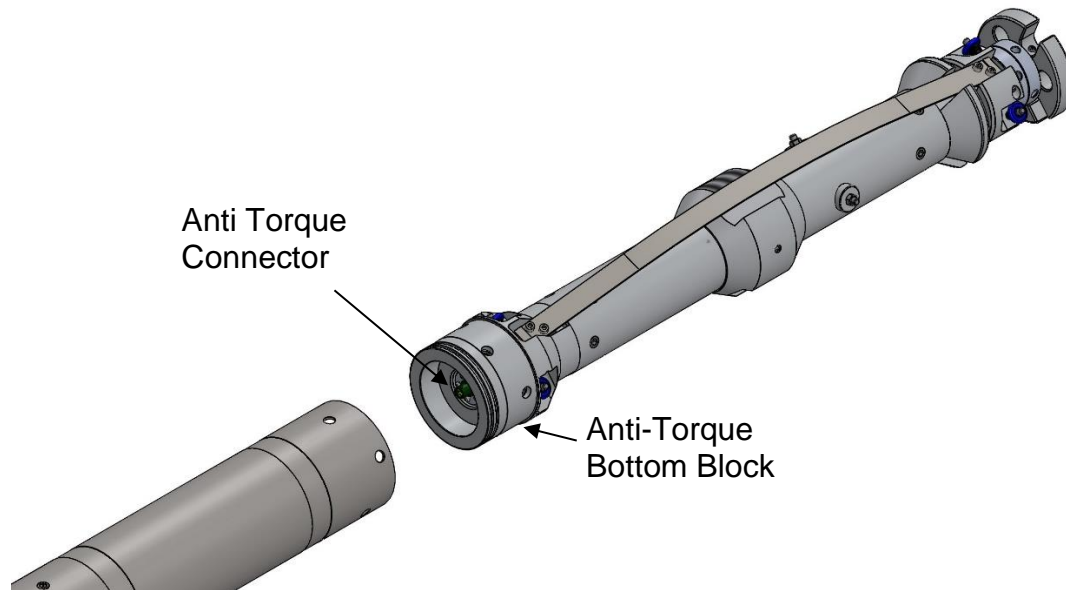


Figure 30 – Anti-Torque to Drill Motor Jumper Cable

Insert the Anti-torque bottom block into the pressure housing of the drill motor assembly. Secure the assembly using the six drill assembly screws provided.

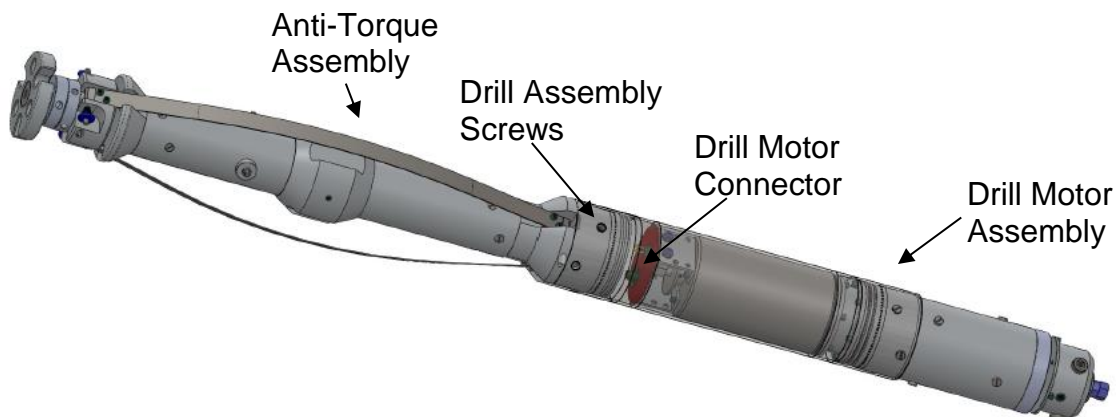


Figure 31 – Anti-Torque and Drill Motor Assembly

2.8.5 Anti-Torque Spring Adjustment

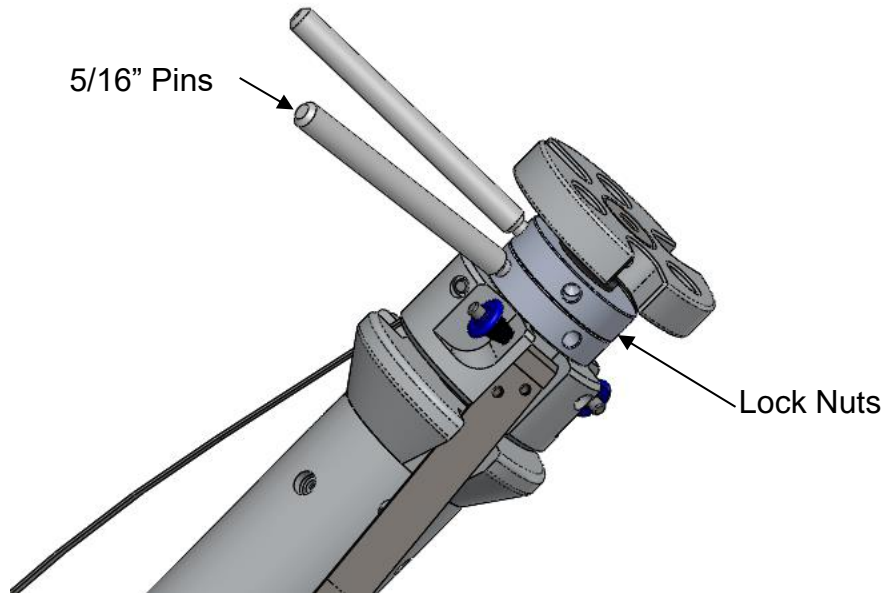


Figure 32 – Anti-Torque Spring Adjustment

After the anti-torque section is reassembled the anti-torque spring tension can be adjusted, and locked. The desired tension is depended on the ice and drilling conditions. This is further discussed in section 4.6. Use the two provided 5/16" pins and the two lock nuts at the top of the drill to adjust and lock in place the spring tension.

2.9 Drill Assembly

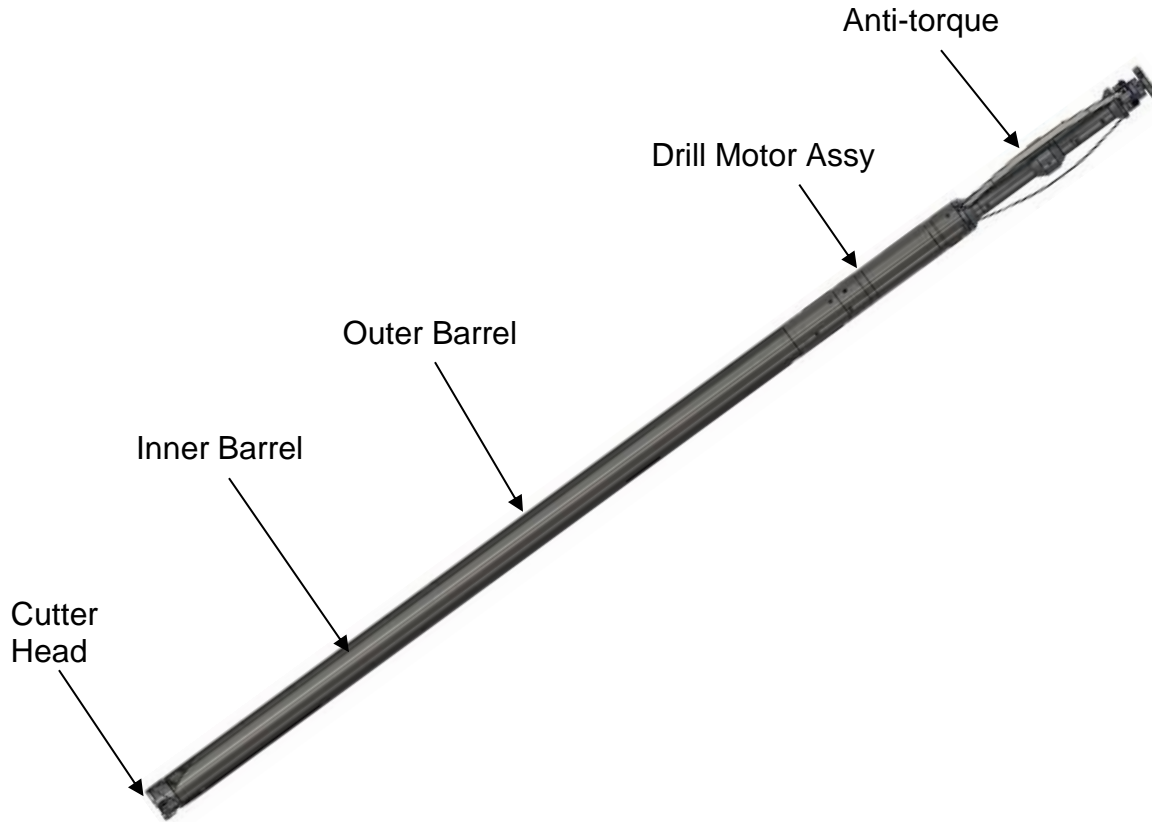


Figure 33 – Drill Assembly

2.9.1 Outer Barrel

Assemble the drill motor section and anti-torque section as detailed below.

Place these two assemblies on top of the boom and secure them using the cradle. Slide the outer barrel over the drill motor section. This is best done by two people as this is a tight fit.

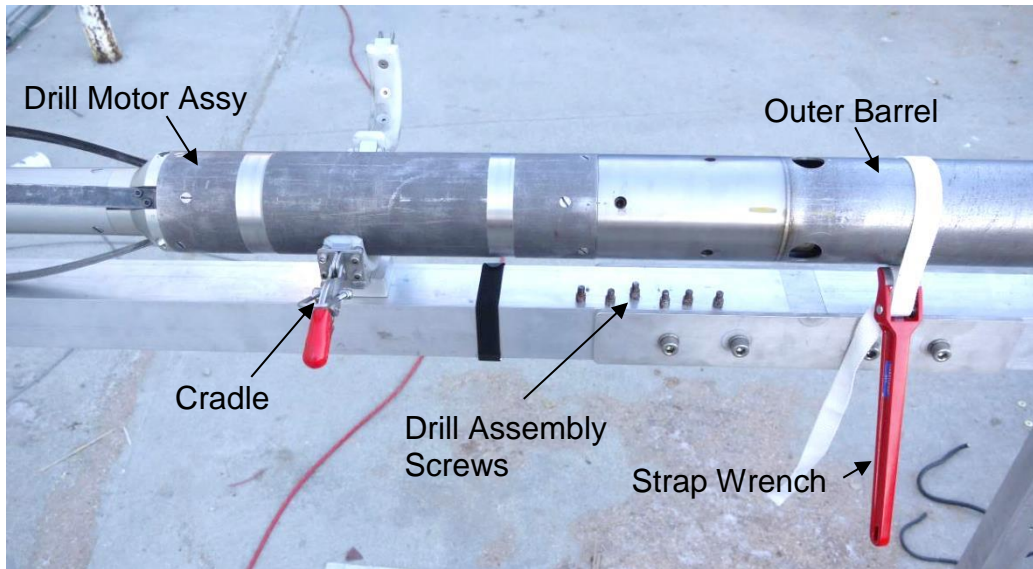


Figure 34 –Positioning the Outer Barrel

There are stamped numbers on both the outer barrel and the drill motor section that indicate the orientation of the two components. The supplied strap wrenches can be used to facilitate turning the outer barrel into position. Once positioned, secure the outer barrel using six drill assembly screws.

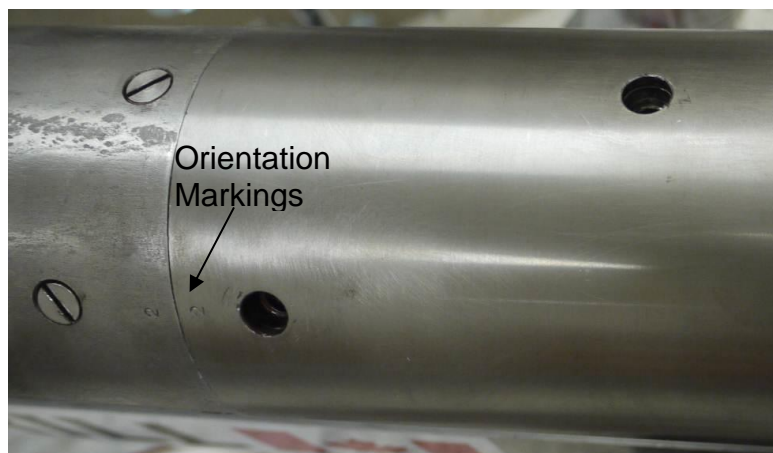


Figure 35 –Outer Barrel Orientation Markings

2.9.2 Inner Barrel

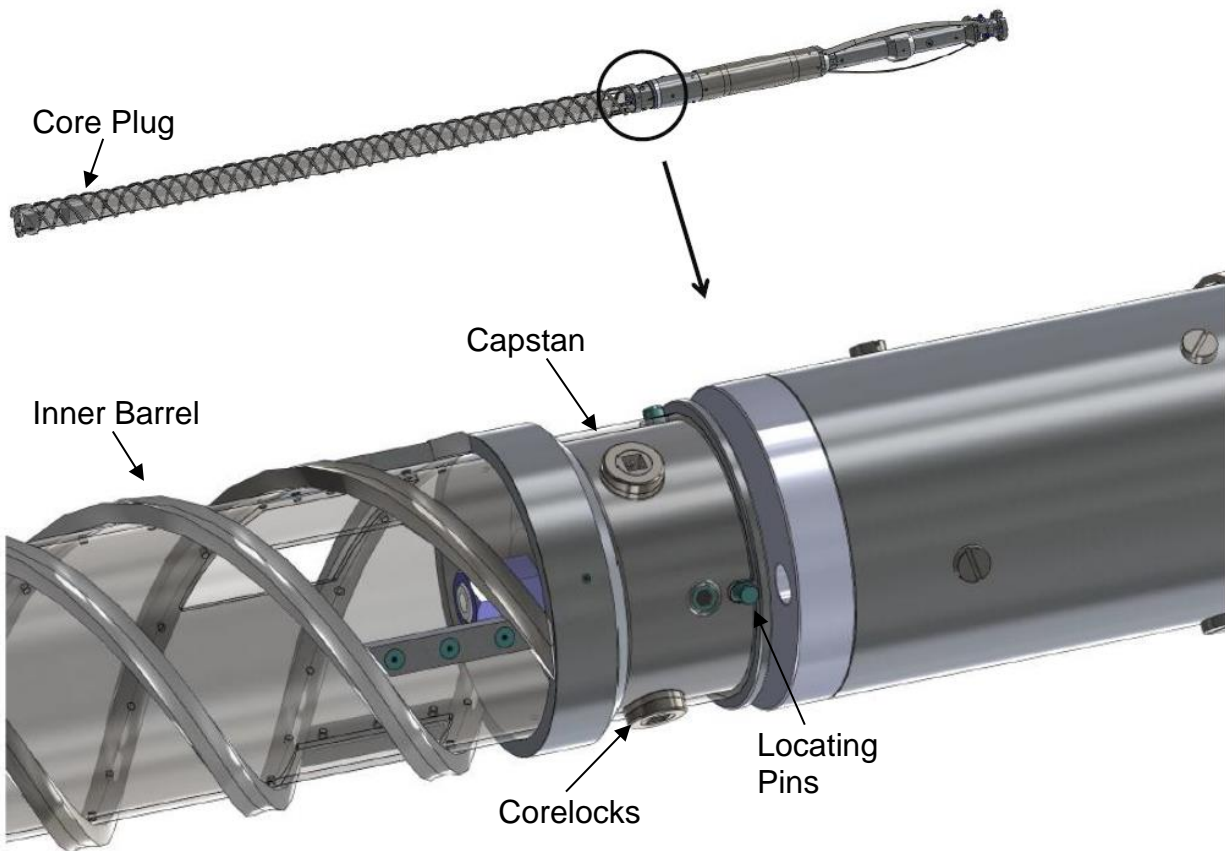


Figure 36 – Inner Barrel Assembly

Insert the Core plug into the inner barrel. This core plug serves to separate the ice core from the chips that are dumped on top. The core plug must always be present when drilling.

The inner barrel is attached to the capstan by three locating pins and three corelocks (see image above). Slide the inner barrel into the Outer barrel turn the inner barrel until the locating pins line up with the notches on the inner barrel. (**Caution:** the cutters are very sharp! Protect your hands from the cutters)



Figure 37 – Engaging the Corelocks

Using the control panel turn the drill slowly until the three sockets for the corelocks are accessible from the three access ports in the outer barrel. Use the provided $\frac{1}{4}$ " hex driver to push and turn the three corelocks into their lock position.

2.9.3 *Installing and removing the cutter head*

The fit between the cutter head and the inner barrel is very tight. Generally, the head should be installed once at the start of the drilling project and removed only at the end when the drill is packed up. Before installing heels and cutters, you can use the dead-blow hammer to GENTLY tap the head onto the barrel. Make sure that the head does not get cocked sideways. The objective is to ensure that the three locking screws line up precisely with the three holes on the inner barrel.

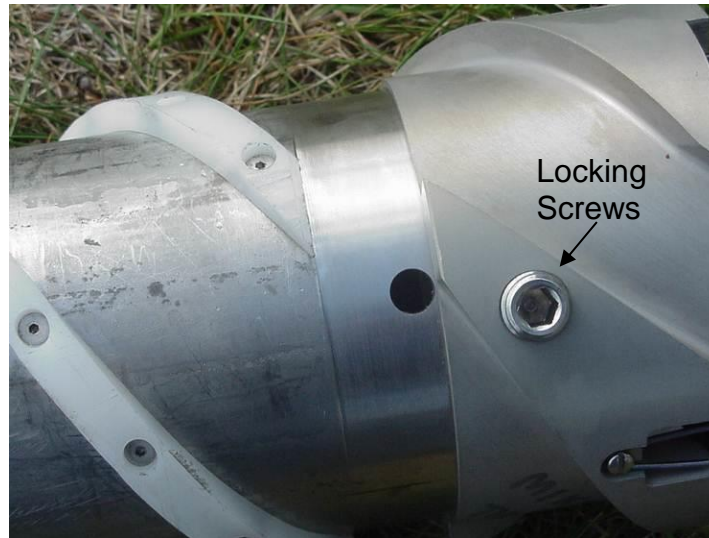


Figure 38 - Installing the Cutter Head

If you are having trouble, you can immerse the cutter head in hot or boiling water – this will expand the aluminum head and will loosen the fit temporarily. If you use this technique, you must somehow dry the head to remove water that might gum up the core dogs during drilling.

To remove the head, disengage the three locking screws, and the gently tap the top side of the spiral flutes with a dead blow hammer and provided nylon rod. Knock each flute once, and then move to the next flute. Do not let the head become cocked on the inner barrel (this will stretch the head permanently) and **do not strike the plastic flights** on the inner barrel.

A dead-blow hammer is a plastic or hard rubber hammer filled with sand or lead shot. **Never use a metal hammer on the cutter head!**

2.9.4 Installing heels and cutter teeth

The three cutters and heels are stacked on pairs of pins on the cutter head. The fit is tight, but this is intentional so that the cutters and heels stay in place.

The heels serve to limit the depth of cut. The heels are numbered and you should always drill with all three heels of the same number. The number represents the nominal cutting distance per revolution in mm. In other words, #4 heels permit up to 4mm of cutting per revolution, although in practice, the cut is shallower.

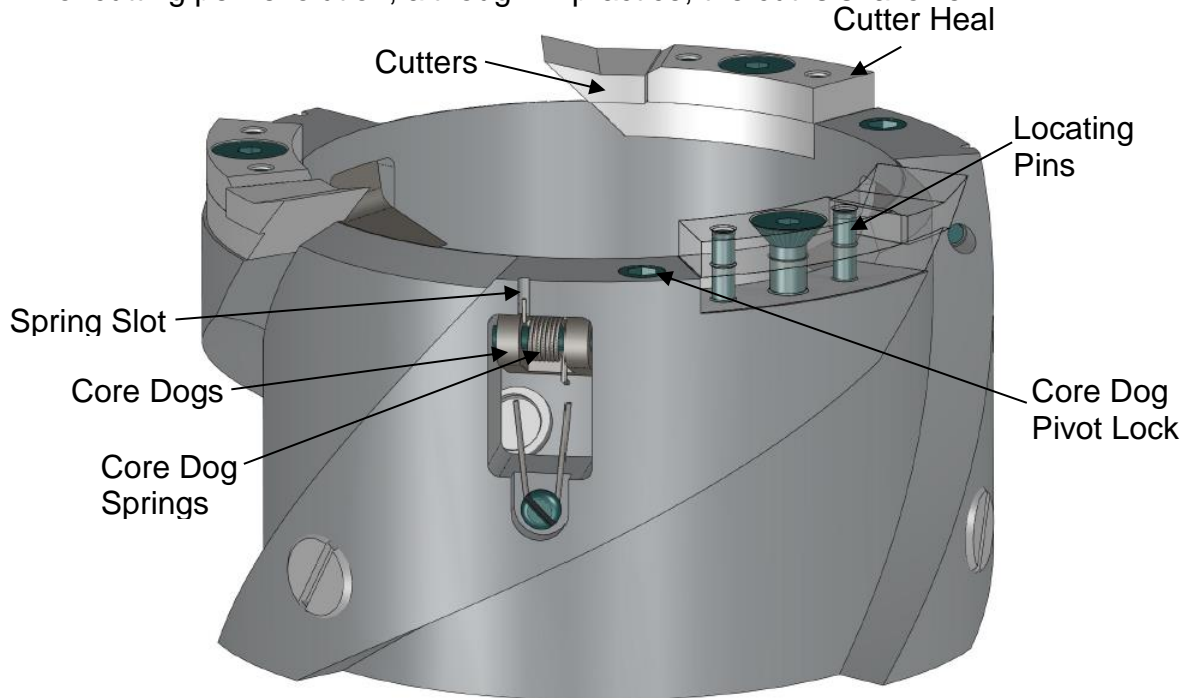


Figure 39 – Cutter Head

2.9.5 Installing the core dogs and springs

The core dogs serve two purposes: they keep the core from falling out of the drill, and they break the core when the drill is raised. Weaker Core Dog Springs should be used when drilling in firn (to avoid the dogs “milling” the core). When one drills through the firn-ice transition, stronger spring need to be installed.

To install springs, loosen the core dog pivot lock (a recessed set screw on the bottom of the cutter head as shown in Figure 39). Retract the pivot pin enough so that only one side of the core dog is on the pivot.

Flare the spring so that one arm engages the slot in the head and the other lays on the back of the core dog. Press the spring into the slot until the coil of the spring is lined up with the pivot – with your other hand, press the pivot through the spring and core dog.

Secure the pivot lock set screw.

If you lose a spring, or need one with different strength, it is possible to make them in the field by wrapping spring wire around a mandrel such as a drill bit. See Figure 40.



Figure 40 – Fabricating Core Dog Springs

Note that the ends of the spring should drop into the spring slot on the cutter head – it is important that the spring does not protrude and get caught on the sidewalls of the hole.

3 Operating Instructions

3.1 General Comments

3.1.1 Motor speeds

The tachometers on the control panel display the speed of the winch and drill motors in % of suggested speed. The drill motor should be run at 100% (3750rpm) which will result in a 75rpm cutter head speed. The winch motor should be run at a maximum speed of 100% (3000rpm). If more torque is required for hauling, the smaller drive gear can be put on the motor rather than on the winch drum input shaft.

3.1.1.1 Winch motor

When breaking core, it is possible that the winch motor does not have sufficient torque. In this situation, the hand crank can be used to help the winch motor break the core.

WARNING! Take care that you do not get tangled in the crank when the winch begins to turn!

3.1.2 Winch setup

Make sure that the mast locking pin (3/4" diameter aluminum with handle) is tethered to the winch frame. **YOU DO NOT WANT THIS PIN TO DROP INTO THE HOLE!!!**

Solar radiation can cause the winch frame to sink into the ground. To prevent this, you may want to do the following:

- Clear off loose snow to expose a solid surface for the winch
- Place pieces of plywood under the frame

3.1.3 Drill trench

Unless the long boom option has been included with the drill, a 2m deep trench is required into which the drill can swing. Because the main legs on the winch are splayed out, the trench does not have to be cut very carefully, but you should try to keep it about the same width as your shoulders. The trench should be fitted with steps as access to the trench is required during drilling.

You may want to arrange a removable cover for the trench, both for safety and cleanliness.

It is also suggested that the sides of the trench be reinforced with plywood or beams to help support the drill and to prevent erosion of the sides of the trench.

3.1.4 Trap door

It is strongly recommended that once a hole is started, a trap door be fitted over the hole so that the hole can be covered when the drill is at the surface (the trap door can be operated from the surface with a string).

If something is dropped into the hole, then the provided magnet can be used to attempt retrieval. The core locks are made out of magnetic stainless steel.

The trap door can be fashioned from a piece of plywood with hinges made of fabric or leather straps. Ice screws or nails can secure the straps onto the ice or snow.

3.1.5 Jammed Core Locks

If, during drilling, it becomes difficult to remove a core lock, it may be that snow/chips have packing into the hole. A small amount of anti-freeze will un-stick the lock.

3.1.6 Cautions

- ALWAYS start the drill or winch motors with the speed control set to zero. Starting the motor with higher speed settings may damage the electrical motor and/or the power system.
- Be aware of rotating components in and around the winch and drill.
- The cutting teeth are very sharp and will easily cut clothing and skin.

3.2 Drilling Core

When drilling there is a plastic core plug that floats freely inside the core barrel. This core plug serves to separate the ice core from the chips that are dumped on top. The core plug must always be present when drilling.

To drill core, follow the following procedure:

1. Raise the mast with the drill attached. Reset master depth counter to zero.
2. Insert the mast locking pin. This $\frac{3}{4}$ " diameter aluminum pin should be tethered to the winch frame.
3. Ensure cable is tight and the spring-loaded sheave is seated in the top of the mast (if the mast stop switch is engaged, you will not be able to run the winch motor "UP" – back the drill off slightly).
4. Release the drill clamp and open the trap door.
5. Set the winch speed to zero (this should be done before each trip into the hole), and start the winch motor in the "DOWN" direction with the speed set to zero.
6. When the proper depth is reached (about 50cm above the hole bottom), start the

drill in the “FORward” direction and run the speed up to 100%. Slowly lower the drill until cutting starts (you can see this happen as the drill motor draws more current). You should be able to drill 90-100cm in ice (more in firn) before the drill motor stalls and the current rises. The operator must respond quickly to reduce motor voltage when stalling occurs. The drill motor should not receive more than 2A. Until the anti-torque section is below the surface, the anti-torque action will have to be provided by a human standing in the drill trench. The reason it is important to start drilling before the drill touches bottom is that otherwise there is a risk that “fluff” gets caked onto the bottom of the heels, thereby preventing the cutters from advancing the drill (see notes in troubleshooting section)

7. Stop the drill motor and raise the winch slowly. You should be able to hear/feel/see the core break (except in fragile ice which breaks easily). If the winch motor cannot break the core on its own, you can use the hand crank to assist. For safety's sake, make sure to remove the crank(s) before moving to high speed.
8. Raise the drill (max speed on winch motor is 100% (3000RPM). Slow down as the surface is reached – the winch will stop when the drill trips the mast stop switch.
9. Close the trapdoor (you have one, correct?)



10. Remove the mast lock pin and lower the tower onto the locking pogo stick.
WARNING! Before lowering the mast, check that you do not have a “hanger.” A hanger is a section of ice core that is dangling out the front of the drill. This can happen if the core dogs slip a bit before they manage to grab onto the core. A hanger must be pushed up into the drill by someone who descends into the drill trench – otherwise, there is a risk that the core gets snapped off and falls into the hole.
11. Rotate the Inner Barrel core locks into the down position – this is done by slowly rotating the drill barrel to the positions that expose the core locks through the access holes in the outer barrel. The core locks are rotated a $\frac{1}{4}$ turn using a $\frac{1}{4}$ ” Allen key.



12. Extract the inner barrel by pulling on the cutter head. If the inner barrel does not come out easily, you can knock on the outer barrel with a dead-blow hammer to release it.



13. Shake out the chips located above the core plug. The chips are shaken out the top of the inner barrel. If the chips do not come out, you can CAREFULLY tap the inner barrel with a dead-blow hammer to release them. It can help if you place a screwdriver or dowel through the parallelogram-shaped holes – this will prevent the core plug (and the ice core itself!) from flying out of the barrel. The chips can be collected for analysis (e.g., pollen)
14. Remove the core plug
15. Slide the core out into a bag or tray
16. Reinsert the core plug
17. Reinsert the inner barrel and lock it in place
18. Repeat procedure!

3.3 Record keeping

With each run, you should record the following:

- The run number (increment each time, even if no core is recovered)
- The “up” direction and run number on the bag into which the core is placed.
- Maximum depth reached.
- Length of core recovered.
- Whether the core had a “flange.” A flange is a flaring at the bottom of the core that indicates that the core has broken off right to the bottom of the hole (i.e., it has broken just below where the cutter stopped cutting. This is VERY important because it means that the cumulative core length and depth counter must match at this depth.

This information is necessary to measure core recovery (generally very close to 100% with the ECLIPSE drill) and to make corrections for the depth counter (cable stretch, slippage, etc.)

You may also want to record the weight of the core, number of pieces recovered, etc.

3.4 Zero depth

We strongly recommend that you use the mast stop switch as your zero depth reference. This way, you can push the depth reset button (to make sure the counter is at zero) when the drill hits the mast stop switch. Later, you can add/subtract the constant offset between the cutters and the ice surface from all the depth readings. There is too much chance for human error if you try to do this another way in the field.

3.5 Encoder and depth counter

The encoder supplied produces 512 ppr. The circumference of the cable when lying on the sheave is approximately 90.78cm, so the conversion factor to compute cm/pulse is 0.1772. You may wish to check this conversion factor by performing a calibration.

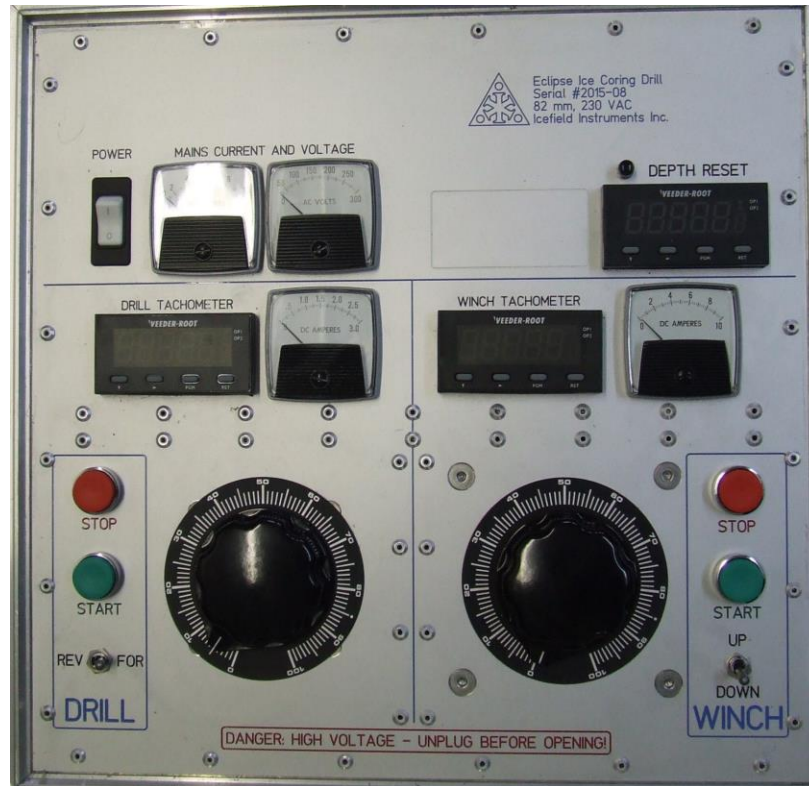


Figure 41 – Control Panel

4 Tips

The following are general tips for drilling and drill operation.

4.1 Drilling a straight hole

Good drilling is a bit of an art. There are several tradeoffs:

- You want big chips to make chip transport efficient (i.e., aggressive cutting)
- You want good quality core with no cracks (i.e., gentle cutting)
- You want a straight, vertical hole, which means you have to use the sonde as a pendulum to find the vertical. If you let all the weight of the sonde rest on the cutters, you will lose the pendulum effect and the hole will eventually curve off to the side.
- You want the anti-torque springs to be tight enough to prevent rotation, yet not so tight that they do not allow the drill to descend easily.

Generally, the weight of the drill is just about right to provide the correct drilling pressure. Nevertheless, the “pressure on bit” will change depending on whether the

winch transmission is warm (cable pays out more easily) and the depth of drilling. Changing ice conditions also mean that different amounts of drill pressure are necessary (for example, in brittle ice (found at 100-150m), you need to reduce pressure to minimize cracking the core.

The best technique for the ECLIPSE drill seems to be to set the winch to pay out cable (but with the speed set to zero, or almost zero) and then to use the hand brake to control the drilling speed, as necessary.

Under some conditions, you can leave the winch in the “UP” position while drilling, thereby applying a bit of tension to the cable and allowing the drill to pull cable off the winch.

4.2 Keeping the drill cold

The ECLIPSE drill works best when it is cold (below freezing) and dry. Water can freeze on drill components, and will tend to gum up the free movement of cuttings.

The sun is your enemy! When the drill is on the surface, solar heating of the drill is rapid. The first place you will notice melting is over the motor section where there is heat liberated by the drill motor.

There are a number of techniques to keep the drill cold:

- Drill at night or, at least, avoid drilling during the heat of the day.
- Drill under cover, or at least arrange a tarpaulin to shield the sonde from the sun's rays.

4.3 Cleaning the drill

We strongly suggest that at the beginning of each season, a short (10m or so) hole be drilled to test out the system and “scrub” the inside of the drill clean. Snow makes an excellent scrubbing powder! The core from this initial hole can be discarded.

4.4 Keeping the drill clean

While drilling, care should be taken to ensure that the flights are cleaner after every run. Any chips stuck on the flights of the inner barrel will impede the free movement of chips while drilling and will result in poor performance. Use the dead-blow hammer (carefully!) and a stiff bristle brush to keep the inner barrel spotless!

It is also important to keep the cutter head clean. At each run, the core dogs should be inspected to ensure that they can swing freely (otherwise you may not be able to retrieve the core you cut!)

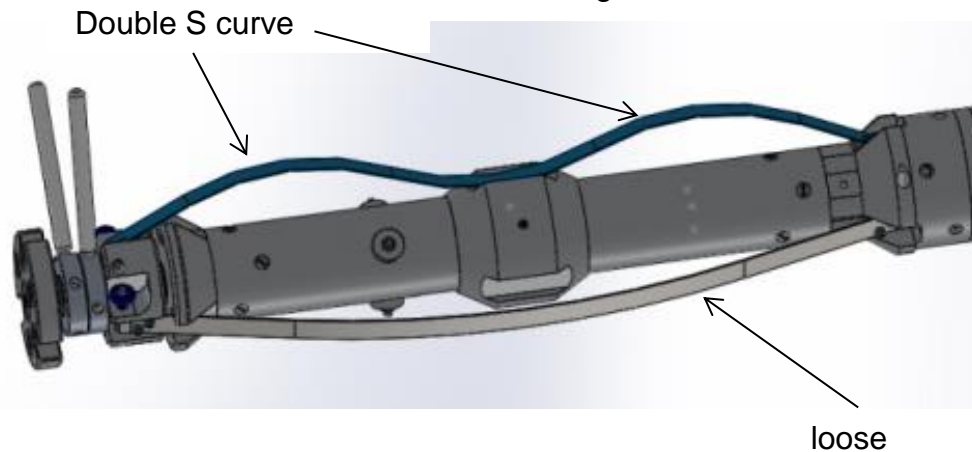
A clean, dry drill is a happy drill!

4.5 Over Night Storage

Frost tends to form in the drill overnight, impeding early-morning operation (the added drag seems to prevent normal chip-transport). To avoid this problem, the last core drilled in the day can be left in the drill and the drill stored at 15-20m depth (below the winter cold wave) overnight. In the morning, the drill is raised to the surface and the core removed – this will ensure that the barrel is clear of frost.

4.6 Setting the Anti-Torque Spring Tension

The anti-torque springs need to be adjusted so that they are tight enough to prevent the drill from rotating when the cutters engage the ice. Generally, the springs need to be tighter in firn than they do in ice. If the springs are too tight, they may prevent the drill from descending easily – you can judge this when you are lowering the drill. Springs that are too loose in firn will “windmill” and cause large cavities to form.



In operation, it is supposed to be tight enough to make the double S curve. The center block forces the spring into a double recurve with 4 separate points of contact 2 on leading edge, 2 on trailing edge.

4.7 “Feeling” the drill

The driller can learn a lot about what is happening down in the hole by placing their hand on the cable. Even at depths of several hundred meters, you can feel exactly when the drill begins to cut core and when something happens (such as the anti-torque springs letting go). This is a good habit to develop.

4.8 Cutter heel choice

The objective when drilling is to produce as large chips as possible (i.e., a high-numbered, thin heel) without having aggressive drilling damage the core (cracking or

making wafers). Big chips transport better and are less prone to sintering in warm conditions.

#5 heels work fine in firn, #4 heels are better in ice. #3 heels cut slowly and in general produce very fine chips that do not transport well and tend to sinter in the flights.

4.9 Losing the lock pins

The inner barrel lock pins are magnetic (martensitic stainless steel) and can be recovered with a magnet if dropped into the hole (although they will tend to drive themselves in firmly after the long drop). Avoid this situation, if at all possible! We highly recommend the use of some sort of “trap door” arrangement which can be closed as soon as the drill is out of the hole.

4.10 Drilling without a Cable Level Winder

It is quite possible to drill without the level winder. The only consideration then is to keep the cable under tension as the mast is lowered, as the geometry of cable path is different without the level-winder mechanism in place. It appears that there is enough motion in the spring-loaded sheave assembly to keep the tension on, but take care to ensure that slack is not formed. If necessary, jury-rig a hooking device on which to manually place a loop of the cable---some experimentation will be required if this proves necessary, but is easy to do. Most drills without a level winder have a “dummy” level winder fitted that keeps proper tension on the cable when the mast is lowered.

5 Eclipse Ice Drill Optional Upgrades

The following describes optional upgrades and their operation.

5.1 Long Boom Assembly

The Long Boom is an optional feature that allows drilling without a drill trench. If your drill is equipped with a standard boom configuration refer to section 2.4.

This configuration of the ECLIPSE ice coring drill is designed so that the requirement for a drilling trench is eliminated. In order to achieve this without shortening the drill sonde (and hence the ice core capacity per trip), the mast has been extended upwards.

Increasing the height of the mast changes the balance point of the winch frame. The standard ECLIPSE frame is balanced such that the mast can be raised and lowered manually (with or without core in the sonde). Increasing the length of the mast changes the balance point and necessitated the following design changes:

- To make transport easier, the mast is broken into two pieces and has reinforcing plates at the pivot point.
- To accommodate the longer mast, an auxiliary “pogo” is provided to give

additional support to the mast when it is in the lowered position.

- An electrically-powered winch and pulley system has been fitted to make raising and lowering the winch easier

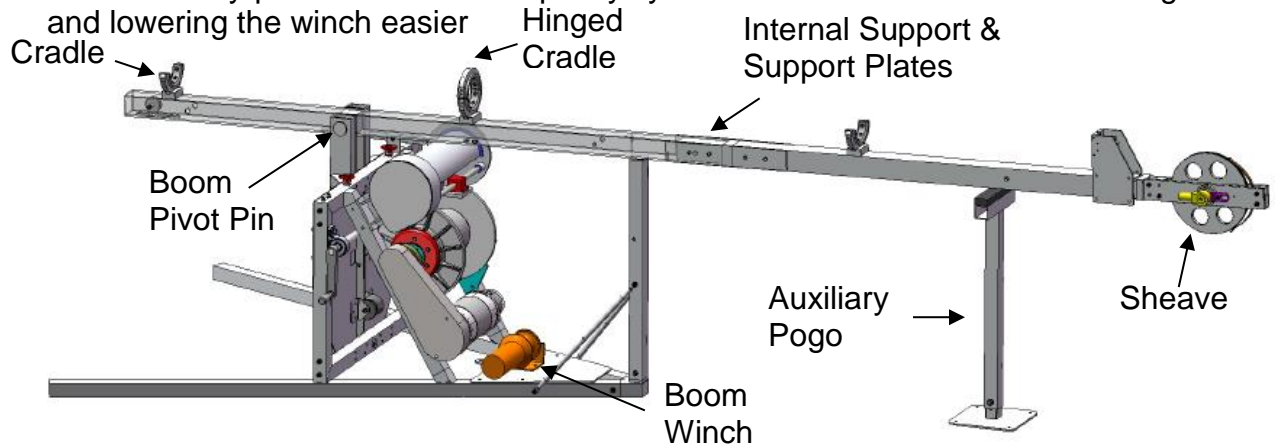


Figure 42 – Long Boom Assembly

5.1.1 Assembly of Long Boom

Assemble the top and bottom section of the boom using the internal Support and Support Plates.

Mount the Boom onto the frame using the Boom Pivot Pin. The Boom Pivot Pin is secured with a supplied hair pin cotter pin. Use the Supplied Auxiliary Pogo to provide support for the boom. The Auxiliary Pogo can be mounted to piece of plywood or other material to increase its stability.

Mount the Boom Stop Bracket at the back end of the boom as shown. Do not over tightening the mounting screws for the bracket. This will deform the boom and cause interference with the sheave.

Mount the cradles as shown Figure 42. The hinged cradle is located in the center position with the other two cradles nearer to either end.

5.1.2 Mounting the Winch

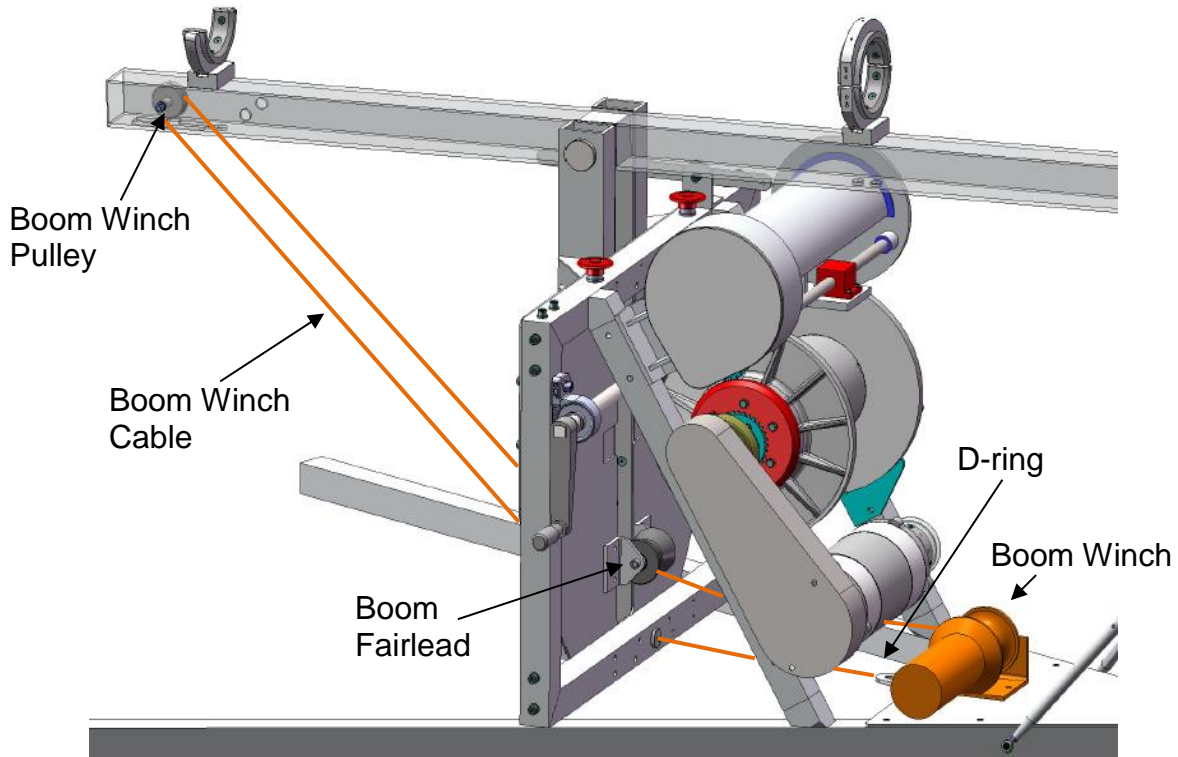


Figure 43 – Boom Winch Mounting

Mount the boom Fairlead onto the face shear plates as shown above in Figure 43.

Mount the boom winch onto the winch mounting plate. Note that the mounting of the winch will differ slightly depending on the winch used. The drill can be supplied with a 12VDC winch, or a 230VAC winch.

Spool out some of the boom winch cable and route it as shown in the Figure 43 above. The cable is attached to the boom support plate using a supplied D ring and can be terminated in a loop using the supplied crimps as shown below in Figure 44.



Figure 44 – Boom Winch Cable Termination

5.2 Wet drill modifications

A wet drilling option is available for the Eclipse Ice Drill. The wet drill modification consists of two additional components: (1) a Tanaka-style booster pump and (2) a bailing system. Additional modifications or items requiring attention are pressure sealing, and cleaning.

5.2.1 Tanaka-style booster pump

To drill in fluid, the normal inner barrel of the Eclipse drill is replaced with a shorter inner barrel above which a combination filter, chip chamber, and booster pump are installed. The booster pump assembly connects to the motor section and rotates while the drill is running. The Figure 45 below shows the booster pump at the right (bottom) with the drive capstan for the short inner barrel partially-obscured. On the left is the filter pancake and the connection to the drill motor drive capstan.



Figure 45 – Tanaka Style Booster Pump

The short inner barrel (see Figure 46) is different from the longer “dry” inner barrel in that it does not have chips ports at the top – just the holes for the core lock pins. This inner barrel also has a small hole at the top to let fluid escape from the inside of the barrel. The same cutter head is used for both the short and long inner barrels.

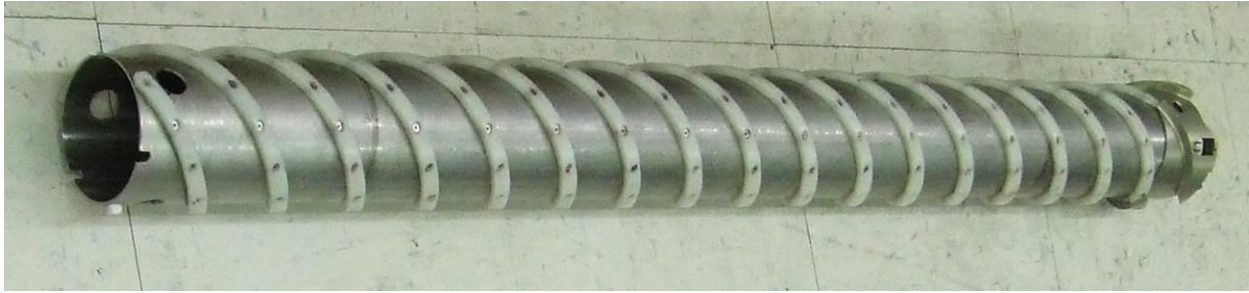


Figure 46 – Short Inner Barrel

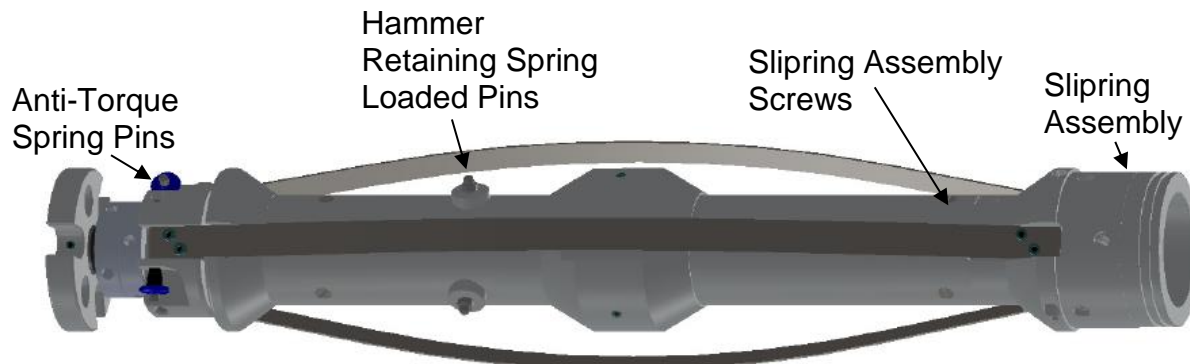
The theory of operation is that the chip/fluid material is carried up the flights of the inner barrel (just like in “dry” operation). Instead of dropping into the inner barrel (as they do in dry drilling with the long barrel), the chips carry on into the booster pump where they are packed into the space below the filter pancake. The filter, of course, lets the fluid through, keeping the chips behind.

The core locks used to attach the short inner barrel to the booster pump are special – they have a lower profile and are curved so that they sit flush with the inner barrel. This minimizes the drag on the chips as they flow past.

5.2.2 Bail

The filter pancake in the booster pump assembly is not perfect – chips will escape and get into the borehole fluid. If drilling in water (fresh or saline), these chips will tend to float to the surface; if drilling in a hydrostatically-balanced fluid, they will remain in suspension.

Either way, it is important that these chips be meticulously removed. If the chips accumulate on the top of the drill as it is being removed, there is a significant risk that the drill gets stuck **under** a pack of chips. The risk is greatest when drilling in water because the chips have a tendency to float to the surface and accumulate.



In order to clean the chips out of the borehole fluid, a bail is used. The bail is attached to top part of the anti-torque section.

- Remove the quick-release pins on the leaf springs (at the top of the anti-torque section)
- Remove the six screws holding the bottom block to the anti-torque tube.
- Carefully remove the bottom block and attached slipring – you will need to release the hammer so that you can push it out the bottom of the anti-torque section
- Remove the ground wire from the hammer, and disconnect the remaining three wires. The three female sockets (these are the ones wired to the winching cable conductors) should be plugged with the dummy pins supplied with the drill (as shown in Figure 47). This is to keep fluid out of the electrical contacts.

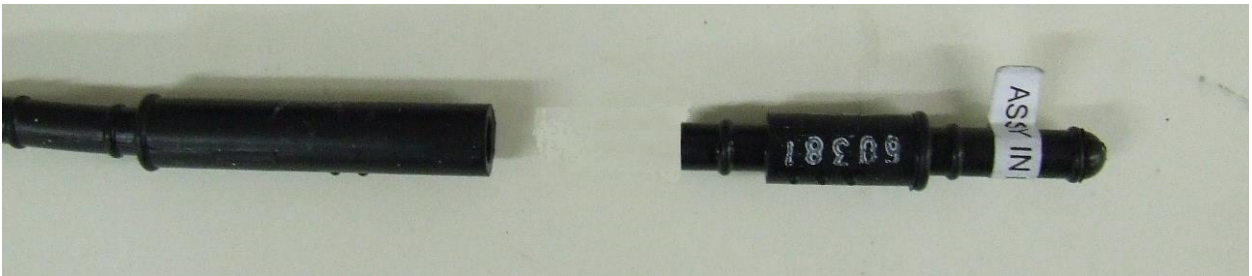


Figure 47 – Seaconn Dummy Plugs

- Return the hammer to its proper locked position.
- In place of the bottom block and slipring, attach the bail assembly using the same six screws.



Figure 48 – Booster Pump Connection

- You can now use the two quick-release pins to remove the bail filter tube easily so that you can make repeated bail runs until the hole is cleaned to your satisfaction.
- Not shown in the above photo is the aluminum sealing ring that improves the seal between the top of the filter tube and the hole wall. The sealing ring is attached using six small pan-head screws and washers.
- At the bottom of the filter tube is a flap-valve assembly that will let fluid flow up through the bail, but not back down. The idea is that the bail can be lowered freely through the fluid, but when it is pulled back up, the sealing ring forces the water flow through the inside of the filter tube and (because the flap valve is closed) out through the filter screen.
- To empty the filter tube, remove it from the anti-torque section using the quick-release pins, and back-flush the filter with fluid poured in through the flap valve.
- Unless there are serious performance issues, it is unwise to try to remove the filter screens from the filter tube. Installing the triple layer of screens (heavy screen in and out, fine screen between) is very difficult.

5.2.3 Assembly and Drilling Procedures

Drilling proceeds in much the same manner as with a dry drill. To start drilling, lay the drill horizontal, and then follow these steps:

1. Load the booster pump into the outer barrel. The filter pancake end goes first. Do not push it in all the way, but leave the capstan sticking out.

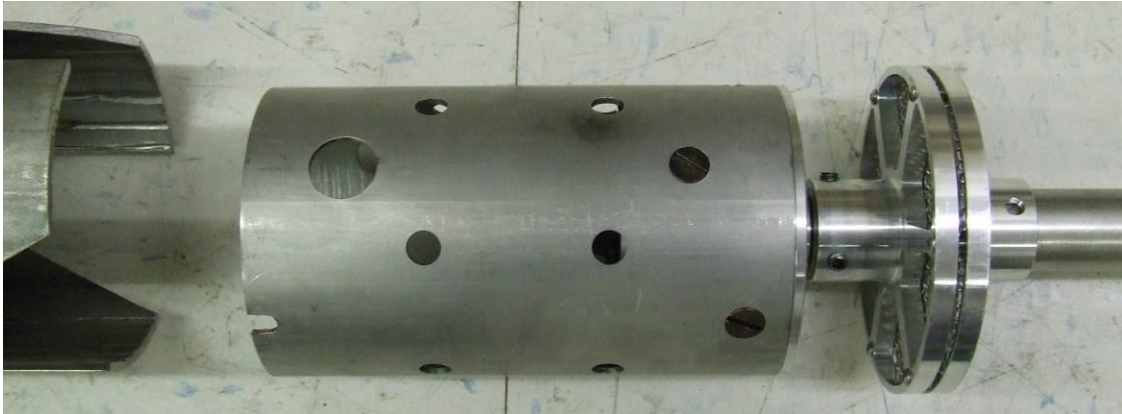


Figure 49 – Inserting the Booster Pump into the Outer Barrel

2. Attach the (short) inner barrel to the booster pump using the short, curved core locks.

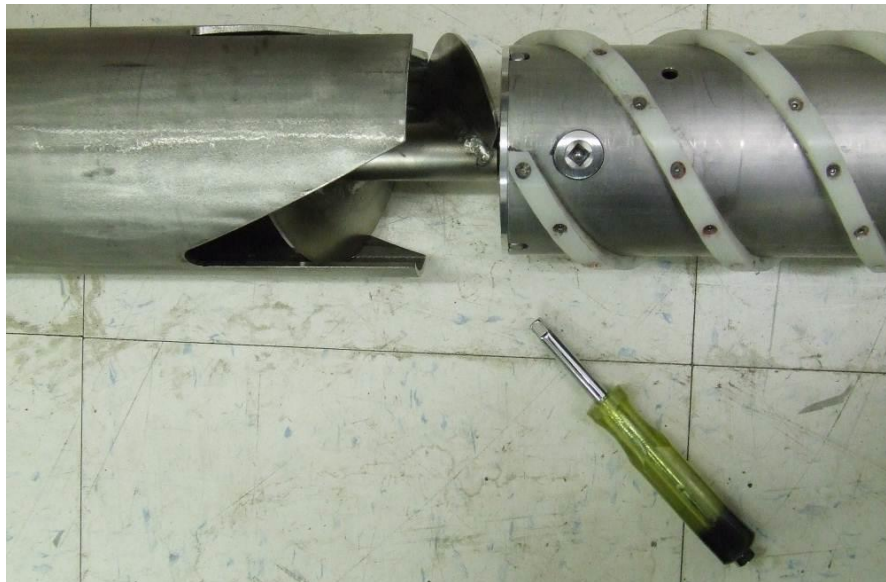


Figure 50 – Inserting the Short Barrel

3. Push the combined booster pump and inner barrel up into the outer barrel and connect the core locks at the top, as per usual.
4. Lower the drill down the hole. You may elect to run the drill at low speed while descending to help the drill “pull” or “suck” its way down the hole. This will also help clean stray chips out of the borehole fluid and may reduce the frequency that bailing is required.
5. Drilling proceeds much as in dry drilling, although the “feel” may be difference owing to the increased power required to drill in fluid vs air (overcoming fluid

viscosity). Monitor the motor current (normally about 1A for dry drilling), but do not exceed 2A (this is the stall current of the motor). If you see a sharp rise in motor current and a drop in rpm, this means that the drill has stalled and drilling should stop. You may elect to run the drill in reverse (**briefly!**) to clear a jam, but the risk is that you dump a lot of chips into the bottom of the hole.

6. After retrieving the drill, reverse the procedure. As with dry drilling, blows with a dead-blow hammer on the outside of the outer barrel can help loosen the chips so that the inner barrel and booster pump can be removed.
7. As the inner barrel is disconnected, you can dump the core out the top directly into a tray or bag.
8. As the booster pump is removed, the wet chips will drop off.
9. Before reassembling the drill for the next trip, make sure that the flights on the inner barrel are completely clear of chips and that the bore is clean.
10. Adjustments can be made to the filter pancake by removing or adding filter elements. A word of caution if you consider removing the fine filter... you may get a lot of fine chips in the borehole fluid and the risk of getting the drill stuck would therefore increase.

5.2.4 Tips

Some wet drilling tips in no particular order:

- Make sure you have propylene glycol on hand and some system to deliver this to the top of the drill should it get stuck
- The square holes in the core locks on the inner barrel can get plugged with chips, so you may need to use a screwdriver to clean them out. A squirt of propylene glycol or propanol may also help.
- If the fluid is corrosive (salty), you need to take special care to disassemble and rinse the drill as much as practicable during operations, and especially before shipping and storage! The aluminum surfaces of the drill (even those that have been anodized) will corrode and expand, causing joints to freeze. Pay particular attention to aluminum- aluminum and aluminum-steel joints. Examples include:
 - Top/middle/bottom blocks of the anti-torque section
 - The cutter head/inner barrel joint
 - The motor section-outer barrel joint
 - The core dogs, heels, and teeth on the cutter head, as well as all springs and fasteners should be removed for shipment/storage and occasionally

when the drill is in use. Pivot pins for the core dogs should also be removed. The only things that can be left on the head are the three backstop wires that prevent the core dogs from rotating back too far.

- The thrust bearings on the hammer are plain steel and susceptible to corrosion. They must be kept clean and dry (certainly not salty) as much as possible or you will be replacing them.

5.2.4.1 Sealing the drill

Because the drill is operating in fluid, sealing the motor section of the drill is critical. The drill motor output shaft has a high-pressure shaft seal installed, and the top of the motor section has a high-pressure slipping.

The O-rings between the motor transmission and the pressure housing for the electrical motor were installed in the factory, but the O-rings on the anti-torque bottom block must be installed in the field.

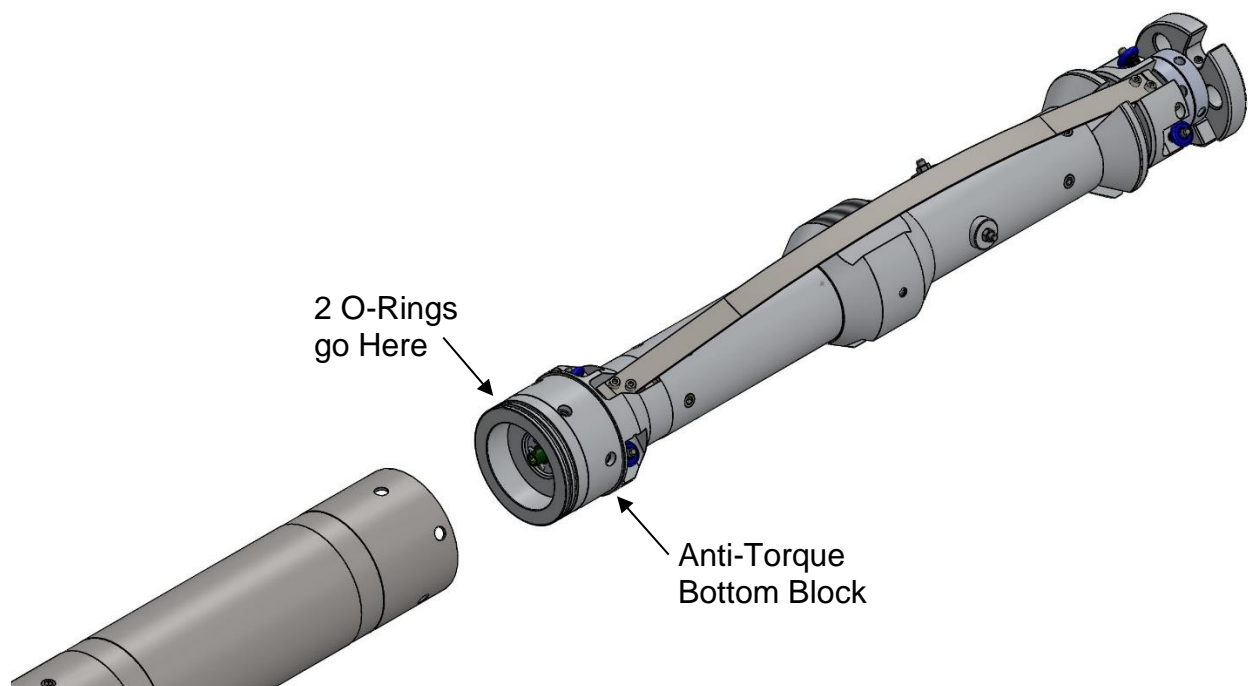


Figure 51 – Sealing the Anti-Torque Bottom Block

It is **critical** that the inner surface of the motor section pressure housing and the O-ring grooves on the bottom block are clean. Spreading some grease on the inner surfaces of the drill motor pressure housing helps get the O-rings over the compression step in the housing (and also helps get the drill apart later). The O-ring size is AS568-154.

It can also help to wipe some grease on the O-rings themselves before assembly. Take care not to nick the O-rings as they pass the mounting holes (if you see any bits of black, you have nicked an O-rings – take it apart, change the O-rings, and try again).

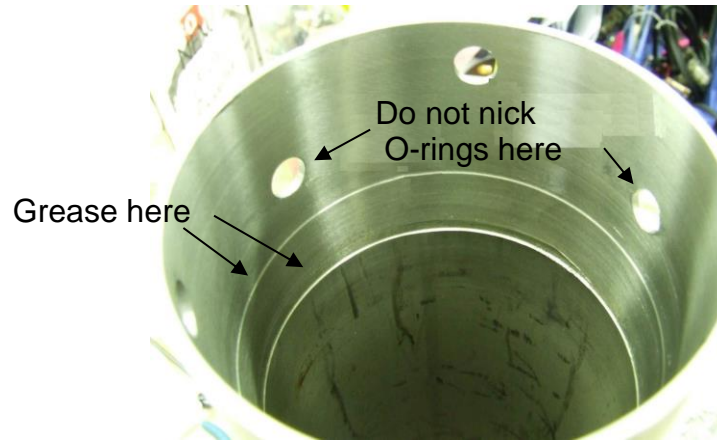


Figure 52 – Installing Pressure Sealing O-rings

6 Routine Maintenance of ECLIPSE Ice Drill

Some routine maintenance is required to keep the ECLIPSE drill running properly and extend its running lifetime.

6.1 Honing the Cutters and Core Dogs

Efficient cutting of core requires razor-sharp cutters and core dogs. Honing these components in the field can be done easily with a fine diamond hone. The cutters and heels are made of hardened O1 tool steel, so sharpening with a file will not work.

6.2 Storing the Drill for the Season

The most important thing to remember when storing the drill away for the season is to make sure it is dry. The control panel, anti-torque section, and drill motor section (especially if sealed) should be dried carefully, inside and out. In other words, the motor section should be opened at the end of the season.

6.3 Saline environments

If the drill is used in a saline environment, corrosion of the aluminum can be a problem. When it corrodes, aluminum forms an oxide (whitish coating) that thickens the surface (i.e., a shaft-like part will expand). Where such a part is inside another (e.g., the anti-torque section in the motor section pressure barrel), the aluminum part may bind inside. For this reason, please rinse with fresh water before moving to a warm, above-zero environment. The drill should be salt-free and dry before shipping and storage.

A clean, dry drill is a happy drill!

6.4 Oil

The Winch motor and the drill motor Harmonic Drive transmissions should be lubricated with Dextron II or equivalent automatic transmission fluid.

The oil level of the winch can be checked with the transmission axis horizontal and the plug hole on a horizontal line through the drum axis. The oil should just reach the plug. The normal contents of the transmission are 375 ml of Dextron II fluid.

The oil level of the drill sonde motor can only be checked by opening the transmission; we don't recommend it. If oil leaks are noticed, please contact us.

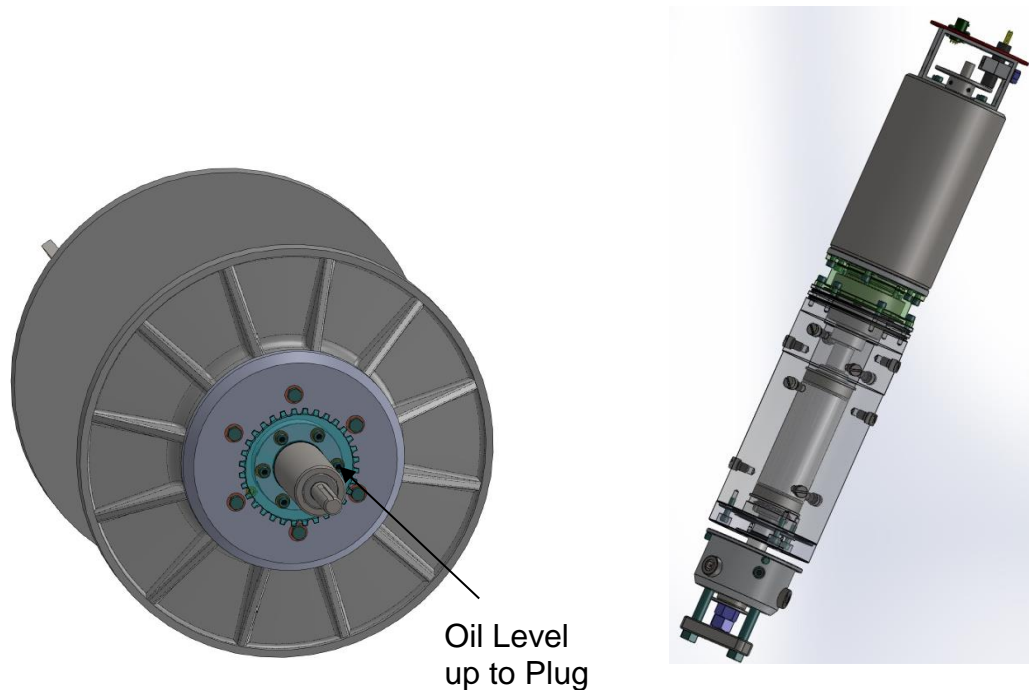


Figure 53 – Winch Transmission Oil Level

6.5 Level Winder Maintenance

With the exception of the enclosed gears which are steel and cast iron, the important operating components and framework components of the Level Winder are made of aluminum alloys, stainless steels, and bronze and so are robust and not subject to corrosion. However, we suggest that you:

- 1) Avoid allowing snow to melt and freeze onto the bellows.
- 2) Periodically grease the linear bearing with a high quality corrosion-preventing grease of NLGI #1 consistency, such as “snowmobile grease”.
- 3) Use a corrosion-inhibiting spray grease (such as a white lithium-based spray grease)

when disassembling and subsequently reassembling the gear train.

4) At the end of every season, dry the LWM thoroughly, and re-grease the bushing bearings.

7 Troubleshooting

The tips below are intended to help an operator problem solve some issues that might be encountered. First check the obvious, such as power connections (recall that the drill motor requires a separate, isolated power feed), and blown fuses.

7.1 Drill motor will not start

There is an interlock operating that prevents the motor from being started if the voltage level to the motor is too high. Ensure that the dial is turned to zero. The drill will not start if the direction switch is in the centre position. Ensure that it set to “FORward” or “REVerse”?.

7.2 Winch motor will not start

- There is an interlock operating that prevents the motor from being started if the voltage level to the motor is too high. Is the dial turned to zero?
- Is the direction switch set to “UP” or “DOWN”? The motor will not work if the switch is in the middle position.
- Is the emergency stop switch connected? The three stop switches (two emergency, one panel-mounted) are all connected in series in a loop. The switches are normally-closed – if any switch is open, or if there is any break in the wires, the winch motor will not start.
- Is the mast stop switch connected? The drill motor cannot be started if the direction switch is in the “UP” position and the mast switch circuit is open (the mast stop switch is normally-closed).

7.3 Depth counter runs in reverse

Either turn the sheave 180 degrees (to move the encoder to the opposite side of the mast), or swap the signal input wires at terminals 29 and 30 (for Hengstler) and 1 and 2 (for Veeder Root) on the depth counter(s).

7.4 Drill motor is trying to rotate the barrel, but not working

Either the drill is packed full of chips and core, or the barrel is frozen (i.e., water frozen to ice) to the outer barrel. In either case, banging the outer barrel with a dead-blow hammer will free the chips. Sometimes, running the drill motor in reverse will clear a “packed” drill.

7.5 Freeing a stuck drill

The worst has happened. The drill has gotten stuck. The response to this situation should be rapid, especially if the drill has been trapped by borehole closure (a danger below about 300m, depending on ice temperature).

- Apply tension on the cable with the winch motor.
- Preferably using a hose or balloon, deliver a “bomb” of anti-freeze (glycol or alcohol) to the drill in order to reverse the freezing or counter the closure.

7.6 “Gum” in the sheave

Particularly with a new cable, you may notice a noxious mixture of cable lubricant and ice chips building up in the groove on the sheave. Clearly this must get cleaned out so that the depth counter can register accurately.

7.7 Winch motor failure

If the winch motor fails while the drill is in the hole, first check that the problem is not simply the fuse on the control panel. If the problem cannot be resolved (e.g., broken generator) it is prudent to get the sonde out of the hole (or at least up to shallow depth where it is accessible). There are two ways to raise the sonde manually

- Using the hand cranks. This is slow and laborious as you are fighting against the winch transmission. You must also ensure that the winch brake (the electric brake) is disengaged. Since electrical power is required to release the brake, this will not be possible in the case of a power outage. In this case, the cover on the rear bell of the winch motor can be removed and the brake carefully unbolted from the motor.
- The sonde can be raised by pulling on the cable. The easiest way to do this is to grab the cable where it descends to the winch drum and walk away from the winch. Wear gloves!

7.8 Winch transmission failure

Since 1996, though ECLIPSE drills have drilled many kilometers of core, we have had one report of the winch transmission failing. When this happens, it is likely that the drill will go into free-fall. If possible, apply the hand brake as quickly as possible to slow the descent of the drill. You may not be able to stop the descent, but the damage will be lessened.

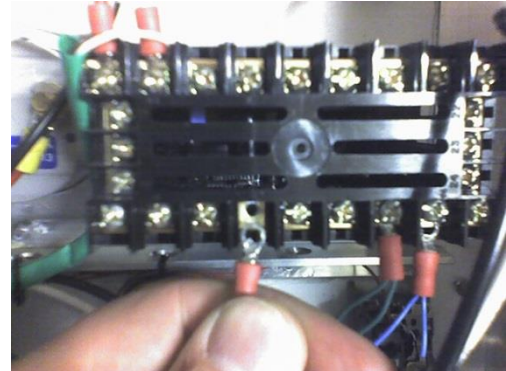
The sonde will then have to be raised using the hand crank.

7.9 The drill does not advance

This problem can be caused by cakes of ice building up on the bottom of the heels. The

best solution is to prevent this happening in the first place:

- When starting a new drill run, always approach the bottom of the hole with the drill running. This will prevent the cutter head landing on the chips that are lying at the bottom.
- Some operators have had luck coating the heels with a thin layer of epoxy – this seems to discourage the formation of cakes



If the drill is in the hole and you suspect that cakes have formed, you can try a few things:

- Reverse the drill motor to try to wipe the cakes off. There is a danger in doing this too much because it will also cause chips that are up in the flights to be driven back down to the cutter head, thereby possible clogging the cutter head.
- You can use the hammer on the drill to “tap” on the drill (while it is running) to try to get the drilling started. You do this by getting a bit of slack on the cable and tapping the hammer by hand.
- You can also raise the drill a few decimeters (by pulling sideways on the cable) and dropping the sonde onto the bottom. If the drill is running, this can knock off the cakes. Of course, this is also hard on the drill sonde!

7.10 Programming the depth counter and tachometers

It has been observed (on one occasion) that the depth counter can lose its programming. This could possibly also happen to the tachometers. For both Dynapar units, there are some parameters that can be changed from the front panel and other advanced parameters that are locked by the grounding of terminal 6 on the back (see photo). To change the advanced settings, unplug the panel from the AC supply and then remove the screw at terminal 6. Then plug the panel back in and press and hold the PGM button for 3 seconds.

7.10.1 Depth counter (Veeder Root C628-70000)

From the front panel, the PGM key will toggle between the depth value (Count) and the Preset1 value (PSEt1) that triggers the alarm. Below the Preset1 value, the display will show RED numbers; above the value, they will be GREEN. The value of the Preset1 value can be changed by using the “>” to select the digit to modify (it will flash) and the “v” to change the value.

When changing the advanced settings, the following values should be used:

Depth Meter		
Setting	Value	Comment
CAL	0.1772	512 ppr (0.0886 for pre 2003 drills @ 1024ppr)
dEcP	0.00	So the display shows m to nearest cm
Count	quAd	Quadrature AB output for depth counter
Up dn	uP	
Input	Sin	
SPEEd	10000	
Opt.	2.00	Time that depth alarm sound in seconds (if installed)
rS En	diS	Prevents RST button from zeroing the depth
COMS	nonE	
Color	Gn_Rd	
Lock	diS	Permits Preset1 to be changed
HELP	HLP Y	
PSEt	2.00	Sets at what values the display changes color

7.10.2 Winch Tachometer (Veeder Root S628-20000)

The table below summarizes the wiring, operation and programming for the winch tachometer:

Programing		
Setting	Value	Comment
InPut	3600	To change this value in the process menu press and hold the V and PGM buttons for 3s
dEcP	0000	
ScA 1	0.00	The input voltage that corresponds to diS 1
diS 1	-200	The value displayed at ScA 1 input voltage
ScA 2	100	The input voltage that corresponds to diS 2

diS 2	200	The value displayed at ScA 2 input voltage
off	0	
Filt	0.5	
Color	Gn_rd	
Lock	diS	
help	HLP Y	
frE9	50	50 Hz for 240V supply
AL 1	P_Hi	
AL2	P_Lo	
Terminal Connections		
Terminal	Signal	Comment
1	V	Tach signal – Note there is a voltage divider on the signal lines using a 10K and 3.3K resistors
2	V+	Tach signal reference
13	AC Power Hot	
14	Ac Power neutral	
Directions		
	UP	-
	DOWN	+

7.10.3 Drill Tachometer (Veeder Root S628-20000)

The table below summarizes the wiring, operation and programming for the drill tachometer:

Programming		
Setting	Value	Comment
InPut	3600	To change this value in the process menu press and hold the V and PGM buttons for 3s
dEcP	0000	

ScA 1	0.00	The input voltage that corresponds to diS 1
diS 1	-156	The value displayed at ScA 1 input voltage
ScA 2	100	The input voltage that corresponds to diS 2
diS 2	156	The value displayed at ScA 2 input voltage
off	0	
Filt	0.5	
Color	Gn_rd	
Lock	diS	
help	HLP Y	
frE9	50	50 Hz for 240V supply
AL 1	P_Hi	
AL2	P_Lo	
Alarm 1	100	Sets the high value at which the display changes color
Alarm 2	-100	Sets the low value at which the display changes color
Terminal Connections		
Terminal	Signal	Comment
1	V	Tach signal – Note there is a voltage divider on the signal lines using a 10K and 3.3K resistors
2	V+	Tach signal reference
13	AC Power Hot	
14	Ac Power neutral	
Directions		
	FWD	+
	REV	-

8 Tools and Spares

8.1 Supplied Tools List

The following tools are supplied with the ECLIPSE ice drill to aid in assembly, maintenance and basic repair:

- 1) 1/4" square drive hand tool for removing core locks x2
- 2) Trimmed 5/32" hex wrench for disassembly of drill motor section
- 3) 5/16" steel pins for adjusting anti-torque section x3
- 4) Hex wrench (Allen key) kit, imperial, 3/8" to 0.050"
- 5) 6" adjustable wrench
- 6) 5" needle-nosed pliers
- 7) Multi-driver screwdriver (flat, Phillips, etc.)
- 8) Blue Loctite thread locker
- 9) 8" diagonal cutters or linesman pliers
- 10) Rubber or plastic-faced hammer
- 11) Dead-blow hammer (plastic hammer with head filled with metal beads)
- 12) Teflon plumbing tape (for water/oil sealing tapered pipe threads)
- 13) Flat screwdriver for cutter head screws and drill assy screws
- 14) Magnet for picking up dropped parts
- 15) Diamond hone for core dogs and cutter teeth
- 16) Nylon rods 10"x1"diam. and 10"x1.5" diam.
- 17) 2 Strap wrench
- 18) 2 set of diamond files
- 19) Hake saw blades
- 20) 10 plastic zip tie
- 21) Roll of Teflon Tape for sealing threads
- 22) Capstan removal tool
- 23) Low temperature grease

- 24) Scotch bright pad
- 25) Sharpies x 2
- 26) Anti-seize compound
- 27) Roll of emeries cloth grit #150

8.2 Suggested Tools List

The following are items that are not supplied with the drill, but it is suggested that they be available for assembling, maintenance and basic repair of the drill.

- 1) Hand-held variable high-speed rotary tool (e.g., Dremel® brand: www.dremel.com) with cutoff blades. This is to assist with cable termination where strands of the winch cable need to be cut.
- 2) 20L of antifreeze to use in case the drill gets stuck in the hole (propylene glycol is preferred as it is aircraft safe and relatively nontoxic – propanol, ethanol, or ethylene glycol may also be used)
- 3) Hose or balloons that can be used to deliver anti-freeze to the drill sonde in case of it getting stuck
- 4) dental pick(s)
- 5) small wire strippers
- 6) fibreglass brush or fine sandpaper for cleaning electrical contacts
- 7) soldering iron and rosin-type electronics solder (this type of resin does not necessarily require cleaning). Do not use organic or acid flux solder!
- 8) color assortment of 22AWG PVC-coated stranded copper wire
- 9) 3/16" heat shrink tubing
- 10) self-vulcanizing electrical splicing tape (or as a poor alternative, electrical tape - splicing tape works better in the cold and leaves no horrible residue). Normal vinyl electrical tape is messy and does not perform well in cold temperatures.
- 11) Sufficient string or cord to lower the supplied magnet to the hole bottom. This may be required to retrieve dropped objects.
- 12) Small vice
- 13) Locking needle-nose pliers
- 14) Scraps of plywood, nails, screws, and a claw hammer

Spare Parts Kit

These lists contain the contents of the spares boxes provided with an Eclipse drill.

For Winch:

Mechanical Components

- 1) 3 ea P.D. drive belt (Eagle)
- 2) 1 ea Harmonic Drive transmission (HDC-040-050-2A)
- 3) 1 ea Spare motor (MET 5A-F014336G)
- 4) 1 ea Spare brush set for MET 5A-F014336G
- 5) 2 ea High-speed bearing for input shaft (61903-2RZ)
- 6) 2 ea Input shaft seal (CR6247)
- 7) 1 ea Output shaft seal (CR12678)
- 8) 6 ea Spare copper washers for transmission bolt seals
- 9) 1 ea Spare O-ring (AS568-255, Viton)
- 10) 1 ea Misc. spare bolts/nuts/washers

Electrical components

- 11) 2 ea Spare control box relay (KUHP-11DT1-12)
- 12) 1 ea Spare reversing switch (7992K10)
- 13) 2 ea Spare rectifier (36MB40A)
- 14) 1 ea Winch wiring tester box
- 15) 1 ea Spare start switch (Telemecanique ZB4BZ101 and ZB4BL3)
- 16) 1 ea Spare stop switch (Telemecanique ZB4BZ102 and ZB4BL4)
- 17) 1 ea Spare depth encoder (Dynapar HS20051263105)
- 18) 1 ea Spare mast stop switch (Honeywell 914CE18-Q)
- 19) 1 ea Spare cable for above (Brad Connectivity 804000A09M020 / Molex 1200650255)
- 20) 1 ea Spare power switch (3120-F321-P7T1-W02D-10A)
- 21) 1 ea Set Molex connector and pins for inside transmission

For Drill:**Mechanical components**

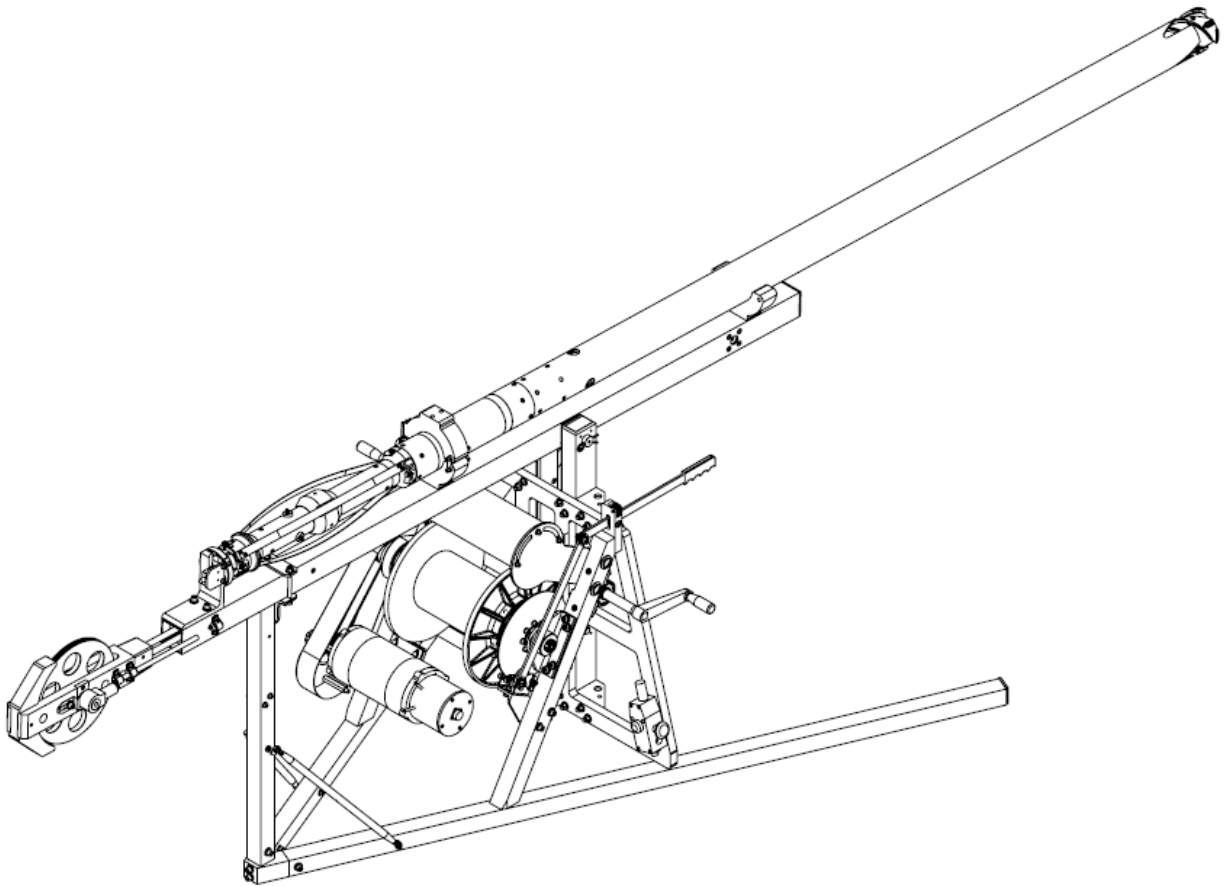
- 22) 1 L Low-temperature Hydraulic oil for slipping
- 23) 2 L ATF Automatic transmission fluid for harmonic drive
- 24) 1 ea Spare motor (MET 3C-D035372C)
- 25) 1 ea Spare brush set for MET 3C-D035372C
- 26) 1 ea Harmonic Drive transmission (HDC-020-050-2A)
- 27) 1 ea Spare music wire in two diameters (2m each) for manufacturing core dog springs
- 28) 3 ea Cutters
- 29) 3 ea Core dogs
- 30) 3 ea Heels (or sizes 3, 4, and 5 – 9 in total – these are operational parts)
- 31) 1 ea Spare set of fasteners for the cutter head
 - a. 3 ea Flat-head screws for retaining cutters
 - b. 3 ea Set screws to secure core dog pivot pins
 - c. 1 ea spare ½-13 cutter head retaining screw
- 32) 2 ea Spare egg/housing for cable termination
- 33) 3 ea Evergrip cable overwrap (one operational, two spare)
- 34) 3 ea Leaf springs for anti-torque section
- 35) 8 ea Spare drill assembly screws
- 36) 3 ea Spare Seacon RMA-MP male plugs for slipping
- 37) 3 ea Seacon RMA Dummy plugs to fit above male plugs when operating with bail (wet drill only)
- 38) 1 ea Spare thrust bearings for hammer (SKF 51103 and 51108)
- 39) 6 ea Pressure barrel sealing ring (AS568-154, Viton)
- 40) 1 ea O-ring/seal kit:
 - a. 1 ea Slipping seal (AS568-029, Viton)
 - b. 1 ea Spline seal (AS568-150, Viton)

- c. 1 ea Motor plate seal (AS568-135, Viton)
 - d. 1 ea High pressure output shaft rotary seal (AHPS R68-0750)
 - e. 1 ea Motor output shaft seal (CR_6X22X7_HMSA10)
 - f. 1 ea Output plate seal (AS568-138, Viton)
- 41) 1 ea Core barrel lock plug
 - 42) 1 ea Capstan puller
 - 43) 1 ft Spare Chain #35, 3/8" pitch
 - 44) 3 ea Chain connecting Link #35, 3/8" pitch
 - 45) 2 ea PRSN_375SN Spring Pin for Hammer Assembly
 - 46) 2 ea Velcro Straps to secure boom cable
 - 47) 1 ea Spare Sheave Spring
 - 48) 1 ea 3A Breaker
 - 49) 1 ea 7 A Breaker
 - 50) 1 ea Misc Heat Shrink tubing
 - 51) 1 ea Run-Hold Switch
 - 52) 1 ea Reset Switch
 - 53) 1 ea 2' length 1/4-20 ready rod (spare for level winder)
 - 54) 1 ea Flight repair kit
 - 55) 1 ea Frame repair kit

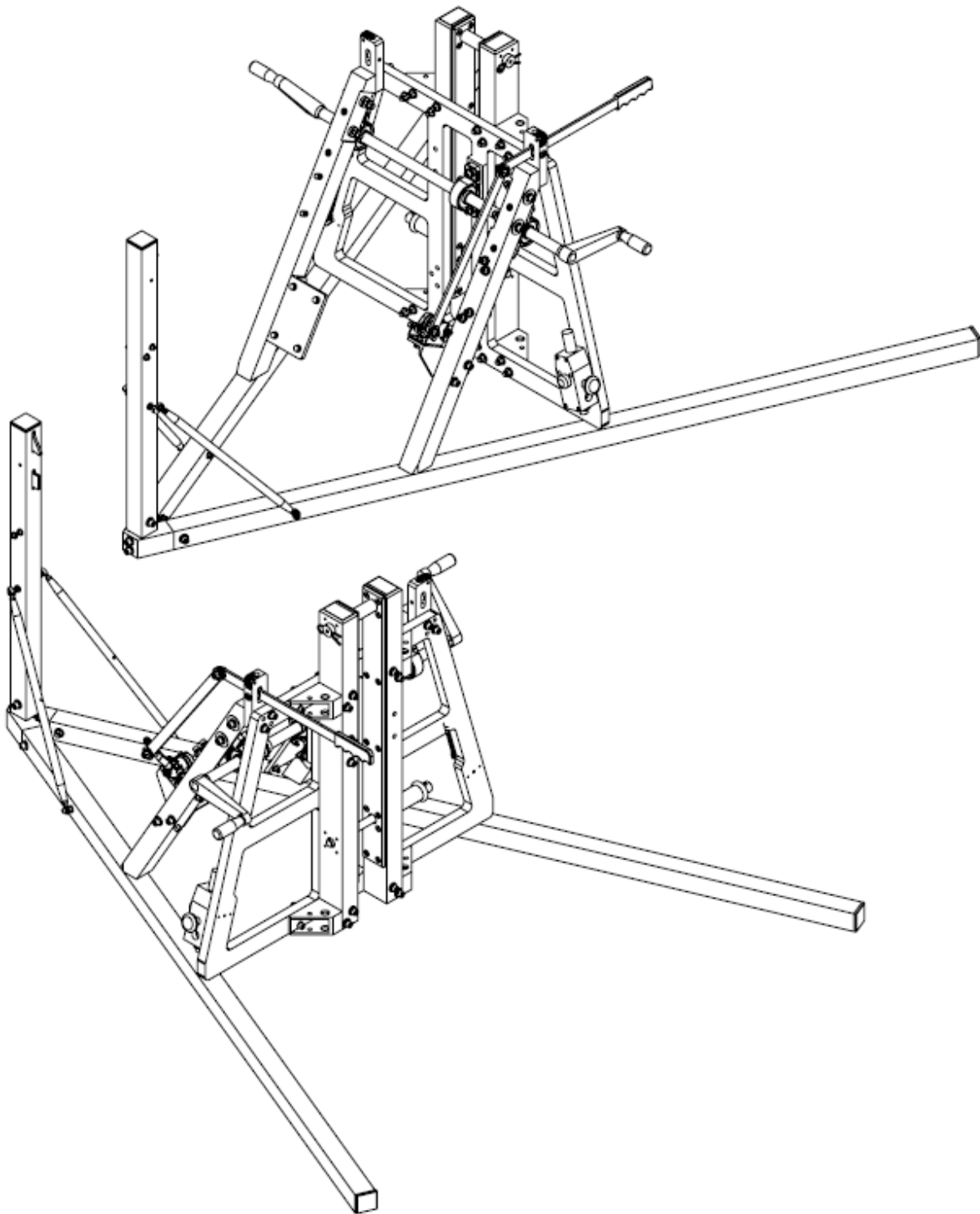
9 Drawings

Those drawings are for information purposes only. Please contact us for more information.

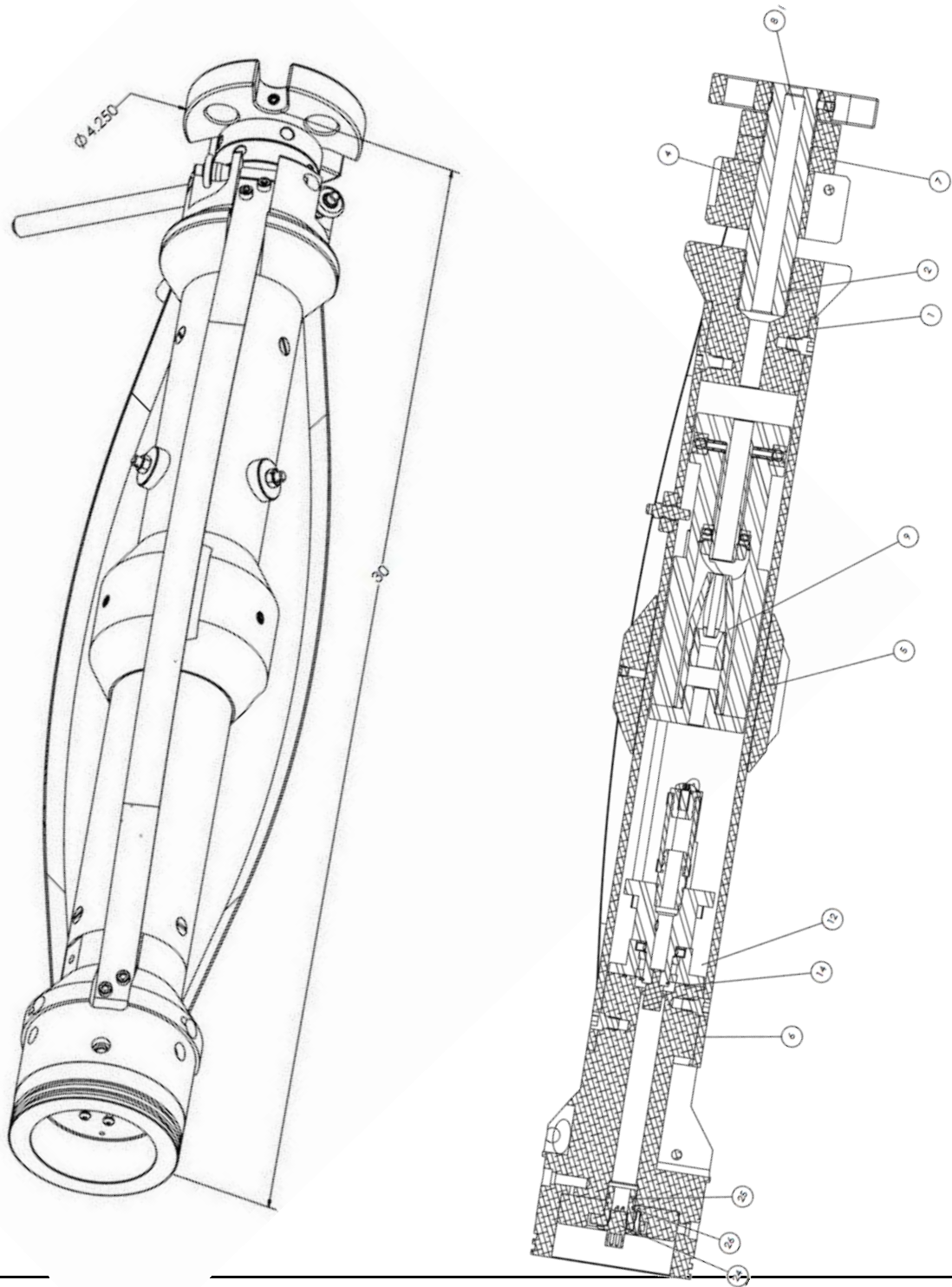
Complete drill short boom:



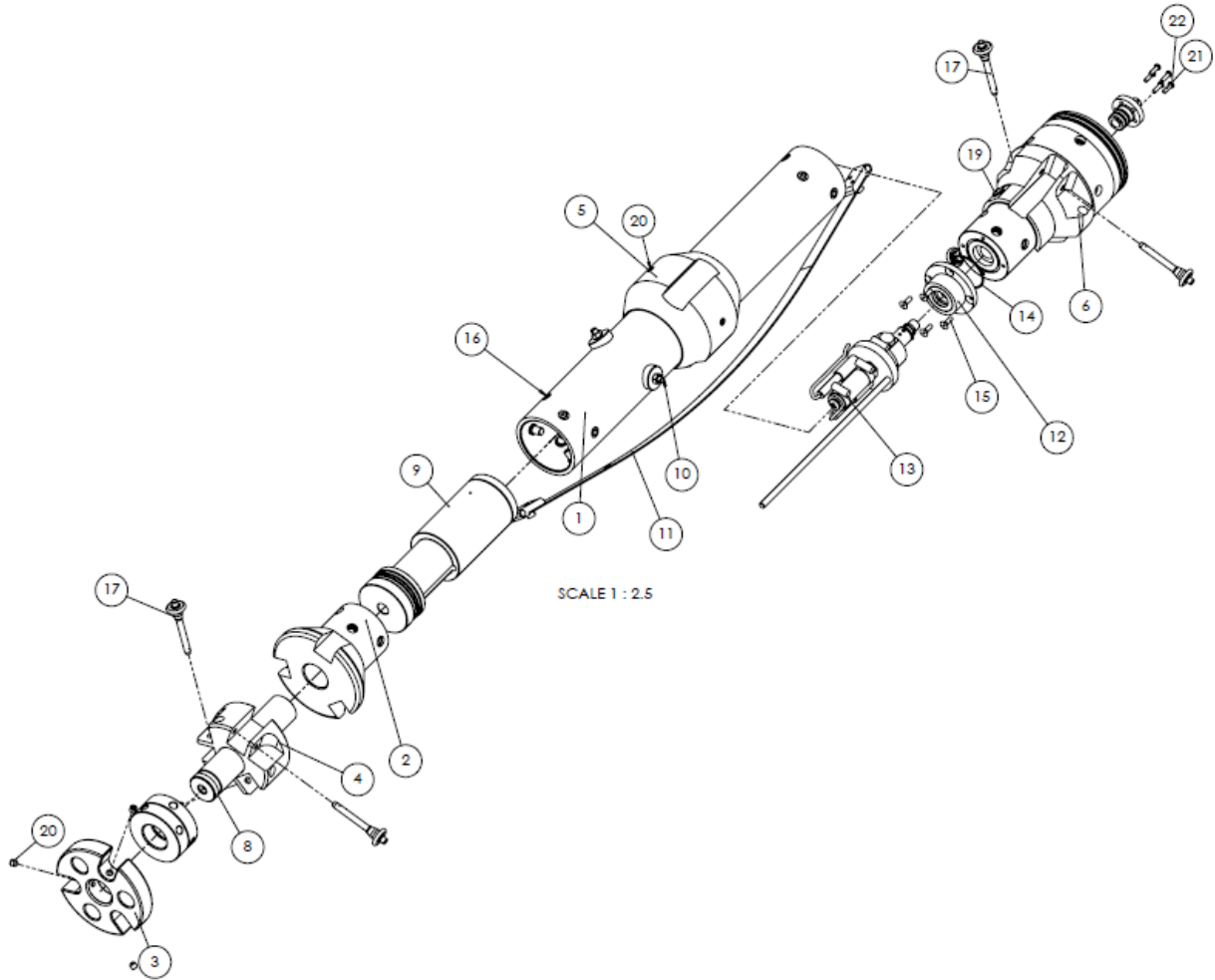
Frame exploded view:



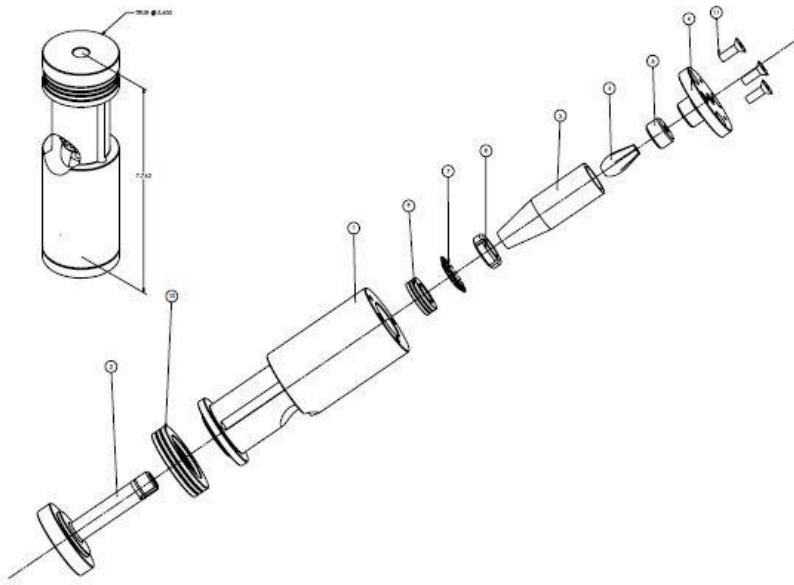
Anti-torque:



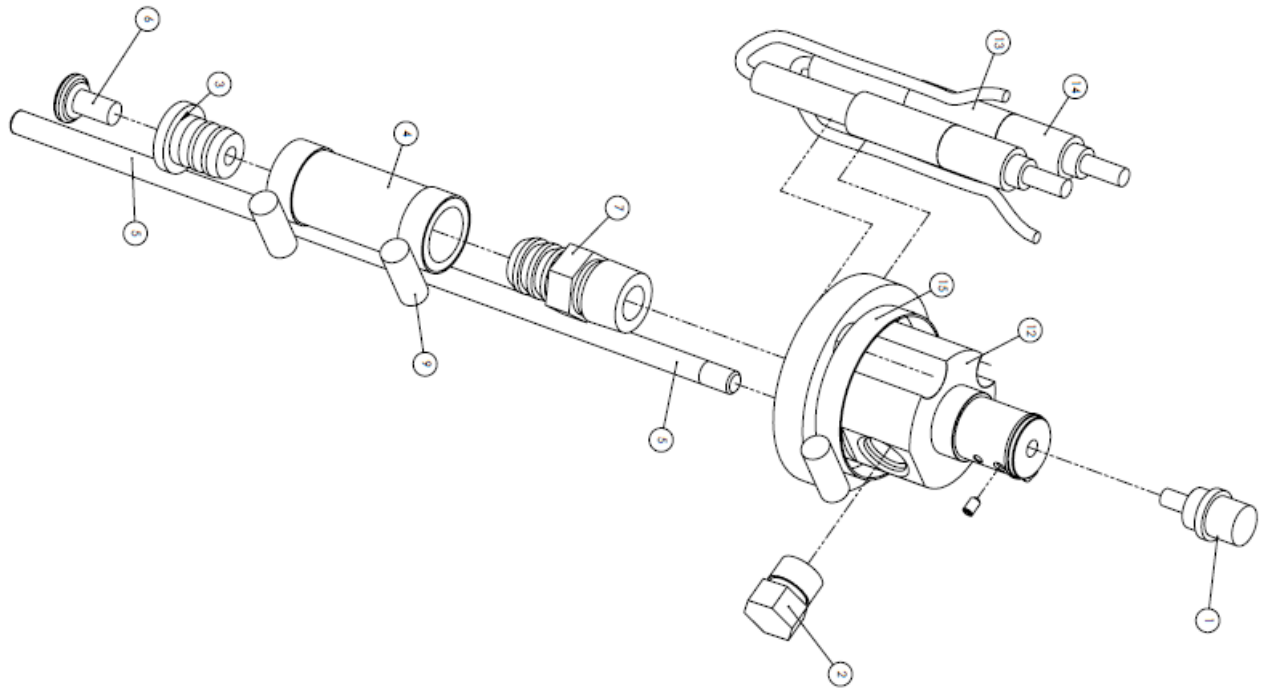
Anti-torque exploded view:



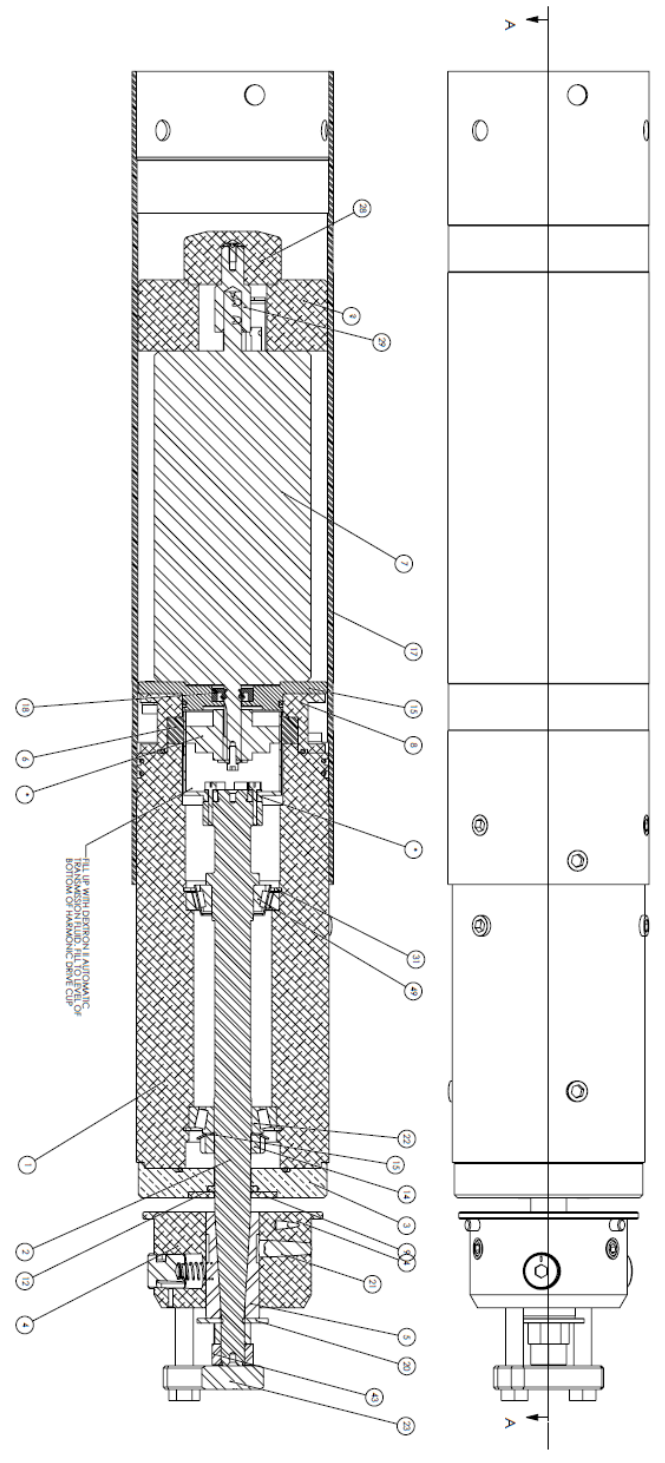
Hammer assembly in the Anti-torque:



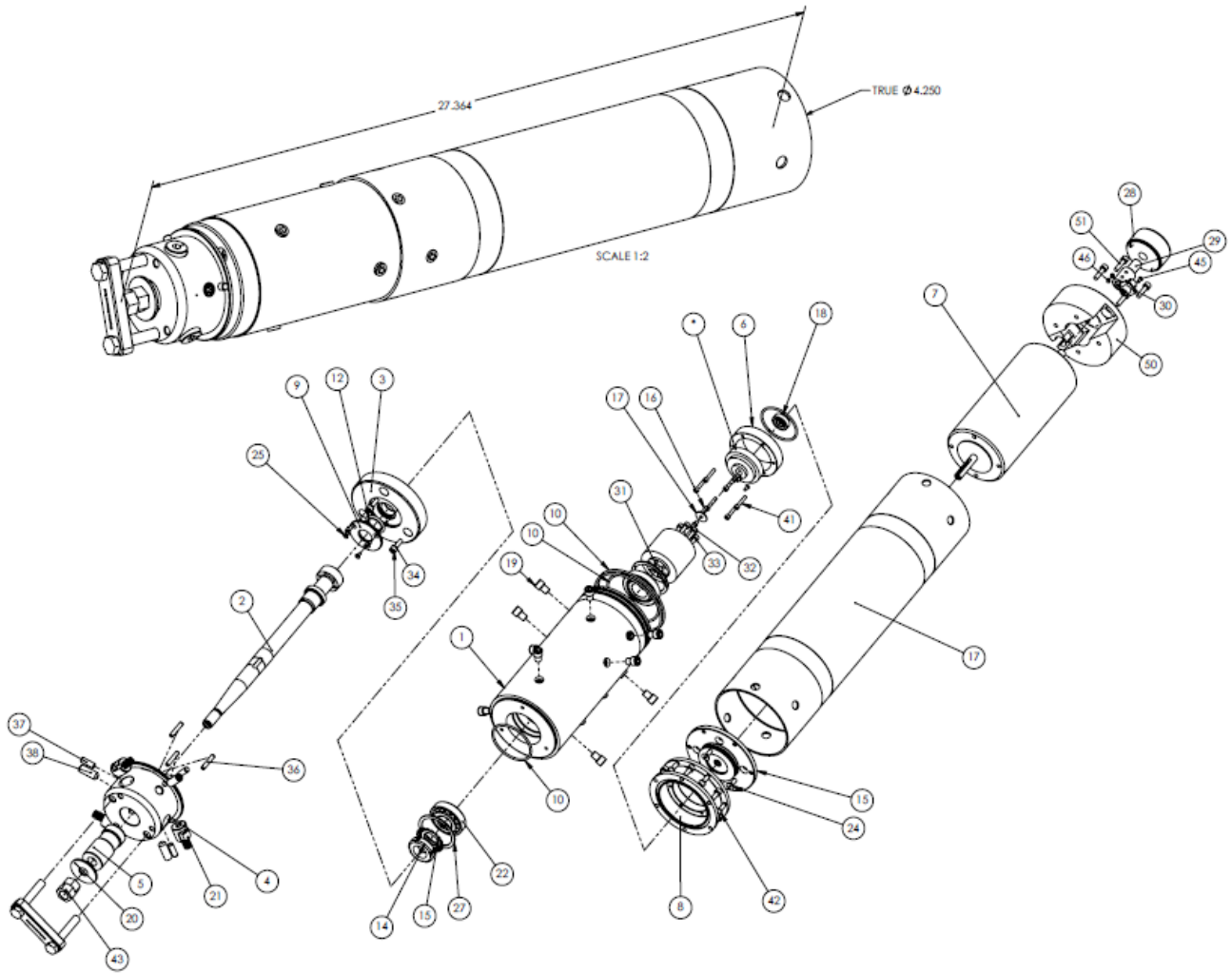
Slip-ring assembly in the Anti-torque:



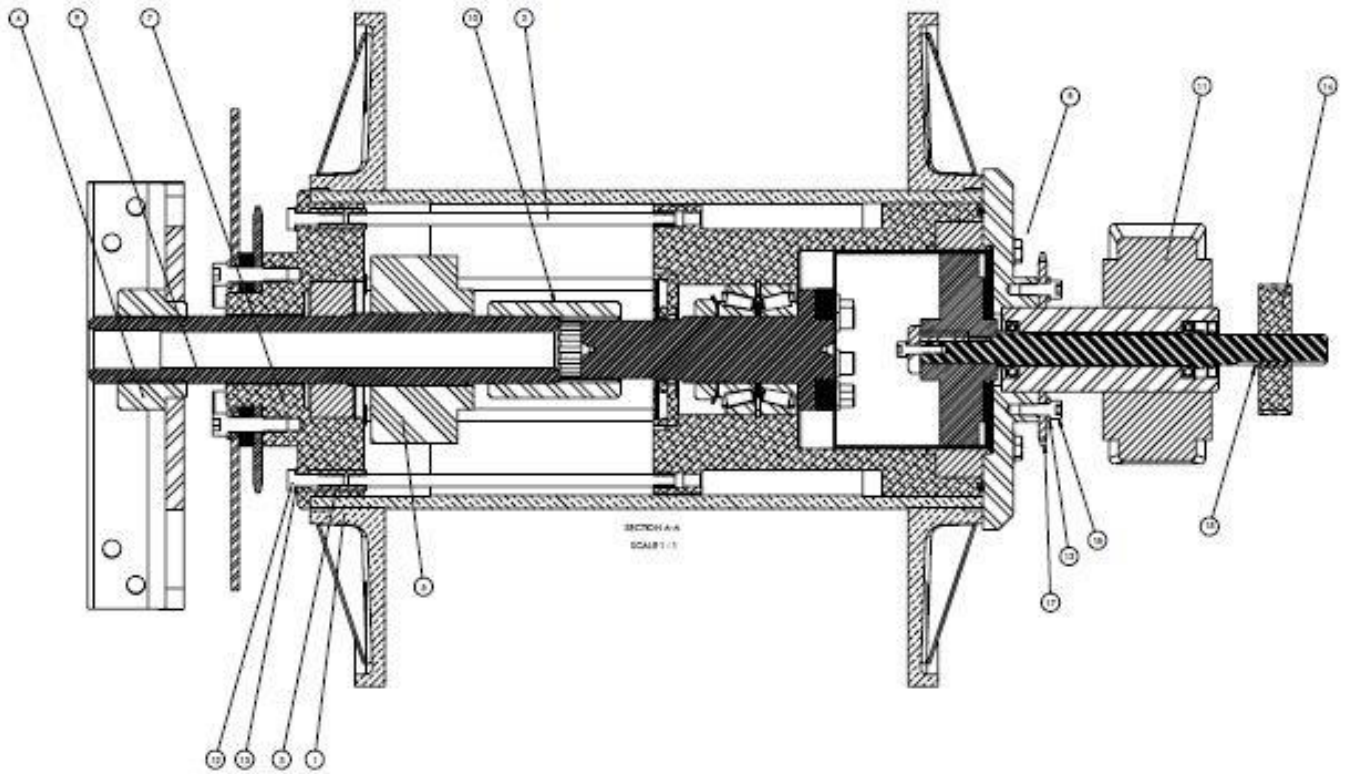
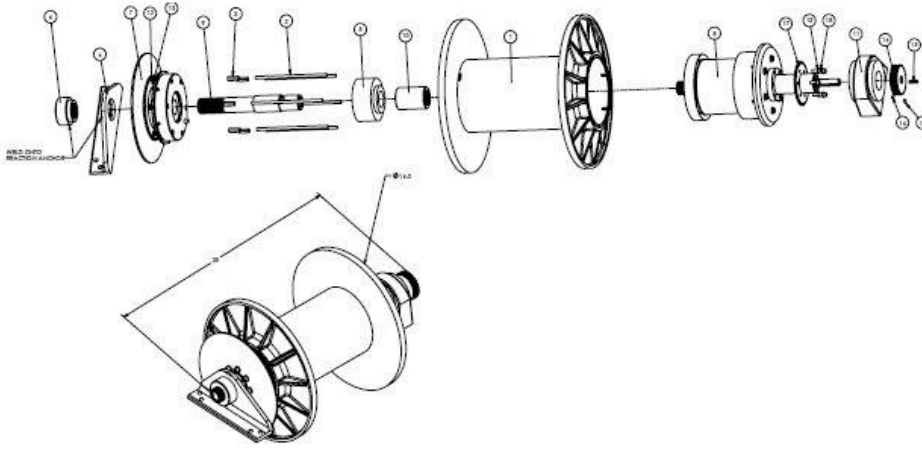
Drill motor:



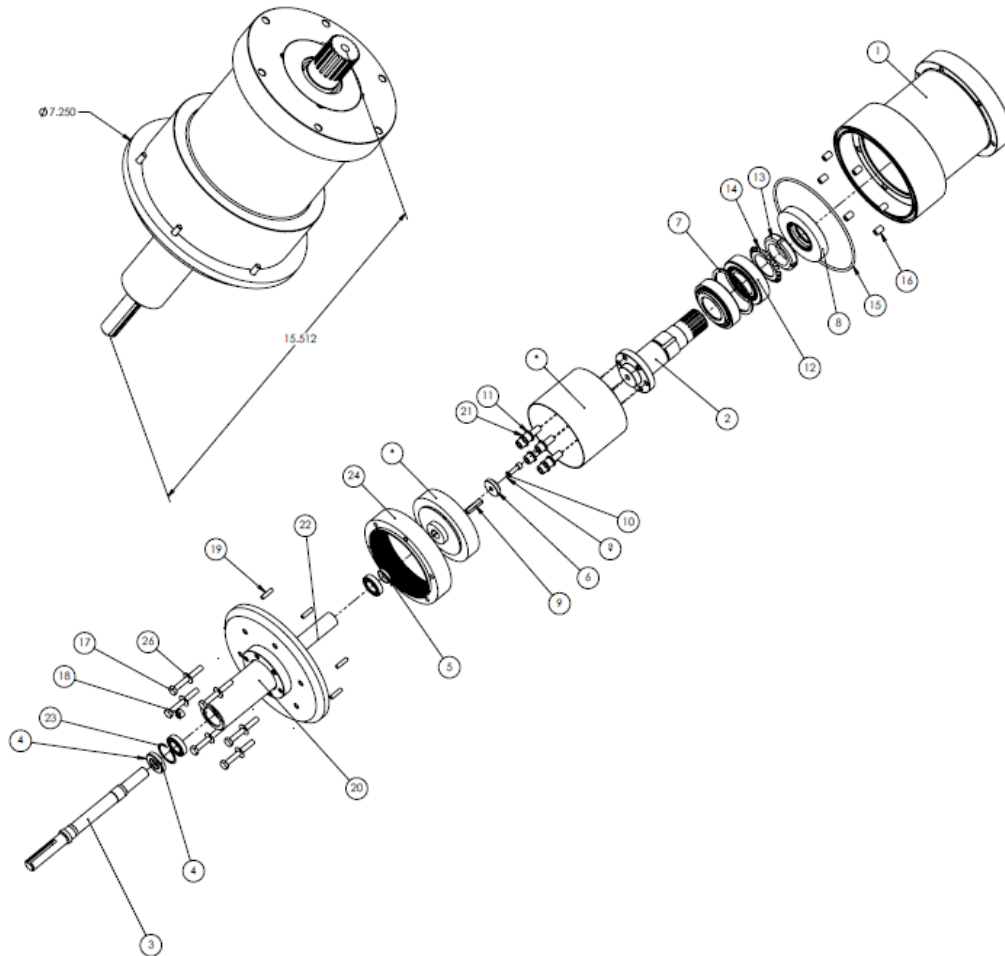
Drill motor exploded view:



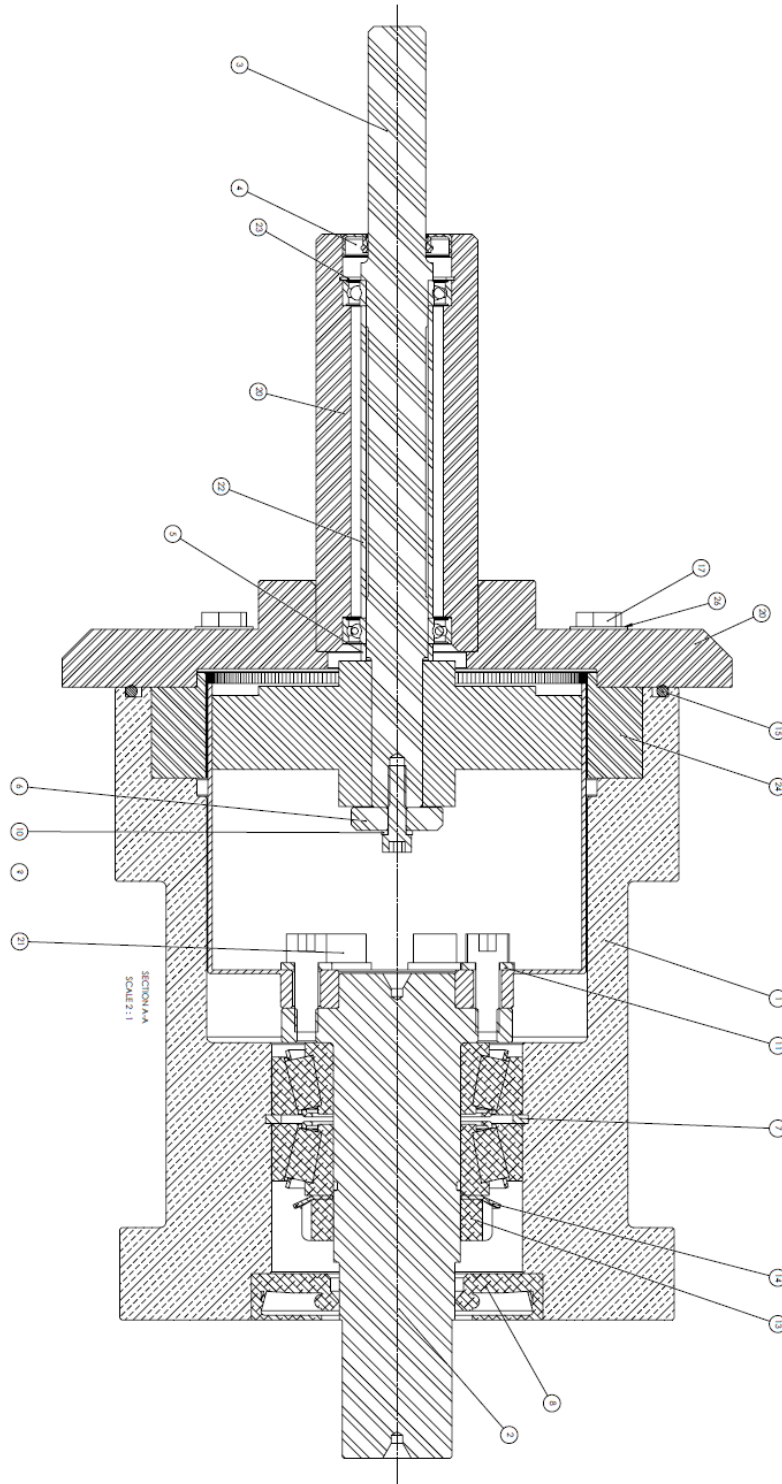
Winch assembly:



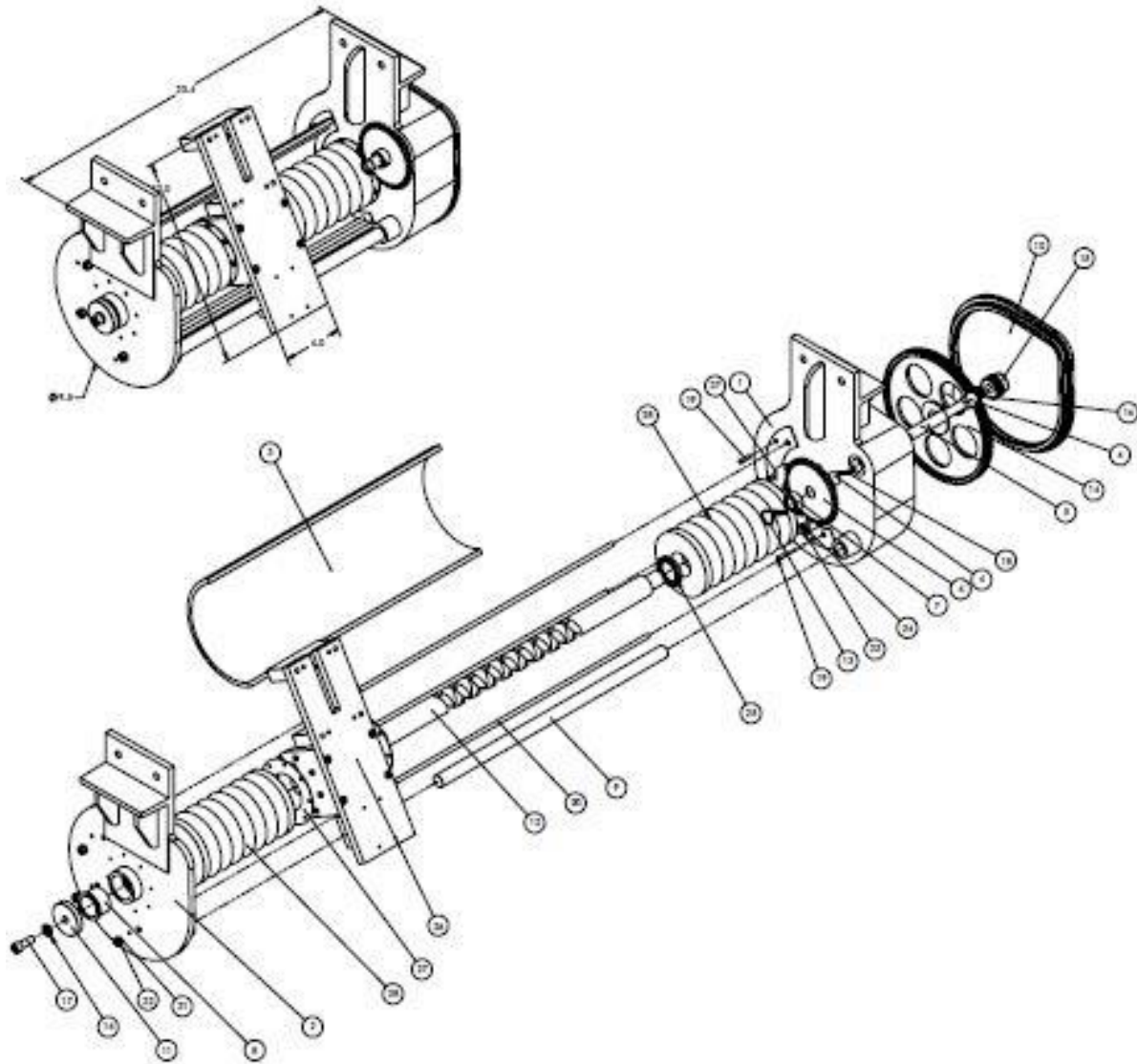
Winch transmission assembly exploded view:



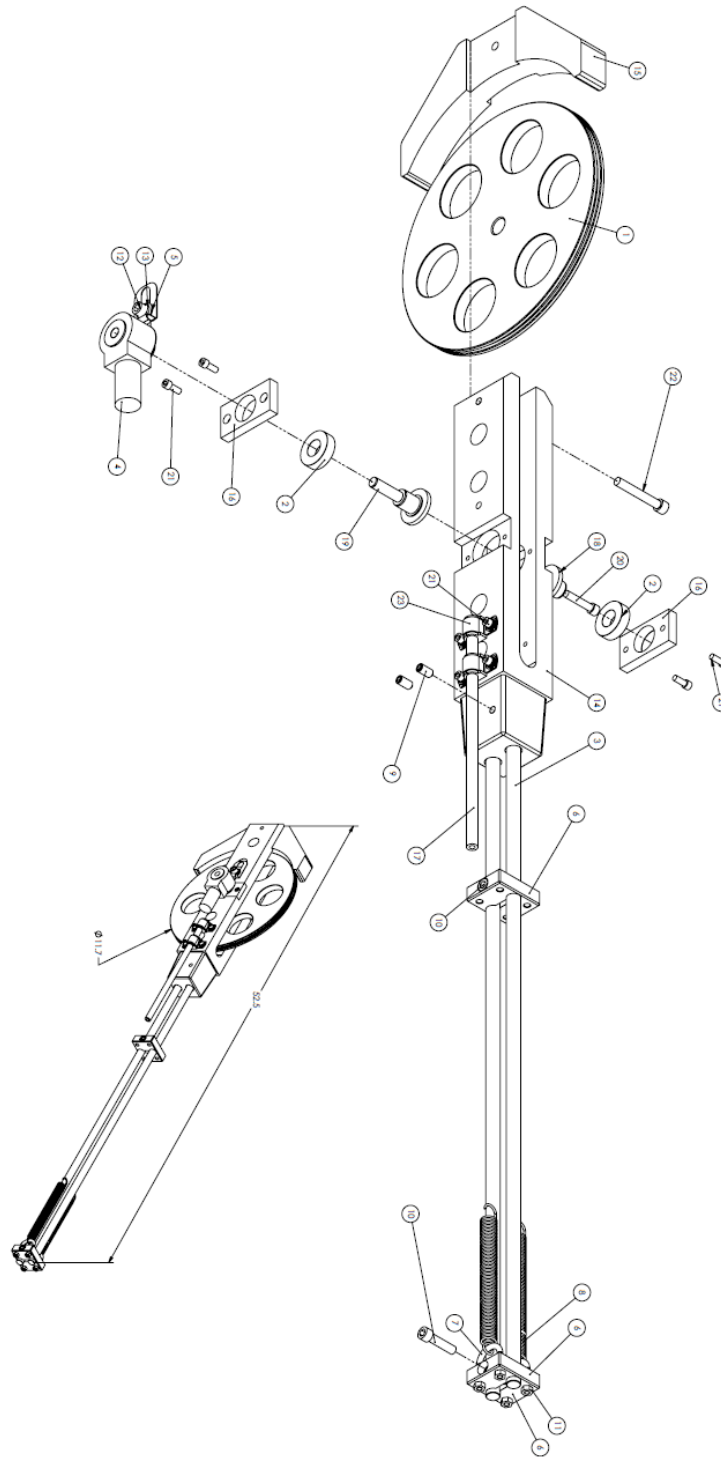
Winch transmission assembly:



Level Winder assembly:



Sheave assembly:



Head assembly:

